EPSON®

Epson Business Solutions

Driven by a relentless pursuit of innovation and market leadership, Epson empowers organizations to achieve their unique goals through a wide breadth of precision-engineered solutions. With a full suite of efficient and compact products ranging from printers to projectors and robots to microdevices, Epson is uniquely positioned to provide enduring partnerships and world-class expertise to those we serve every step of the way.

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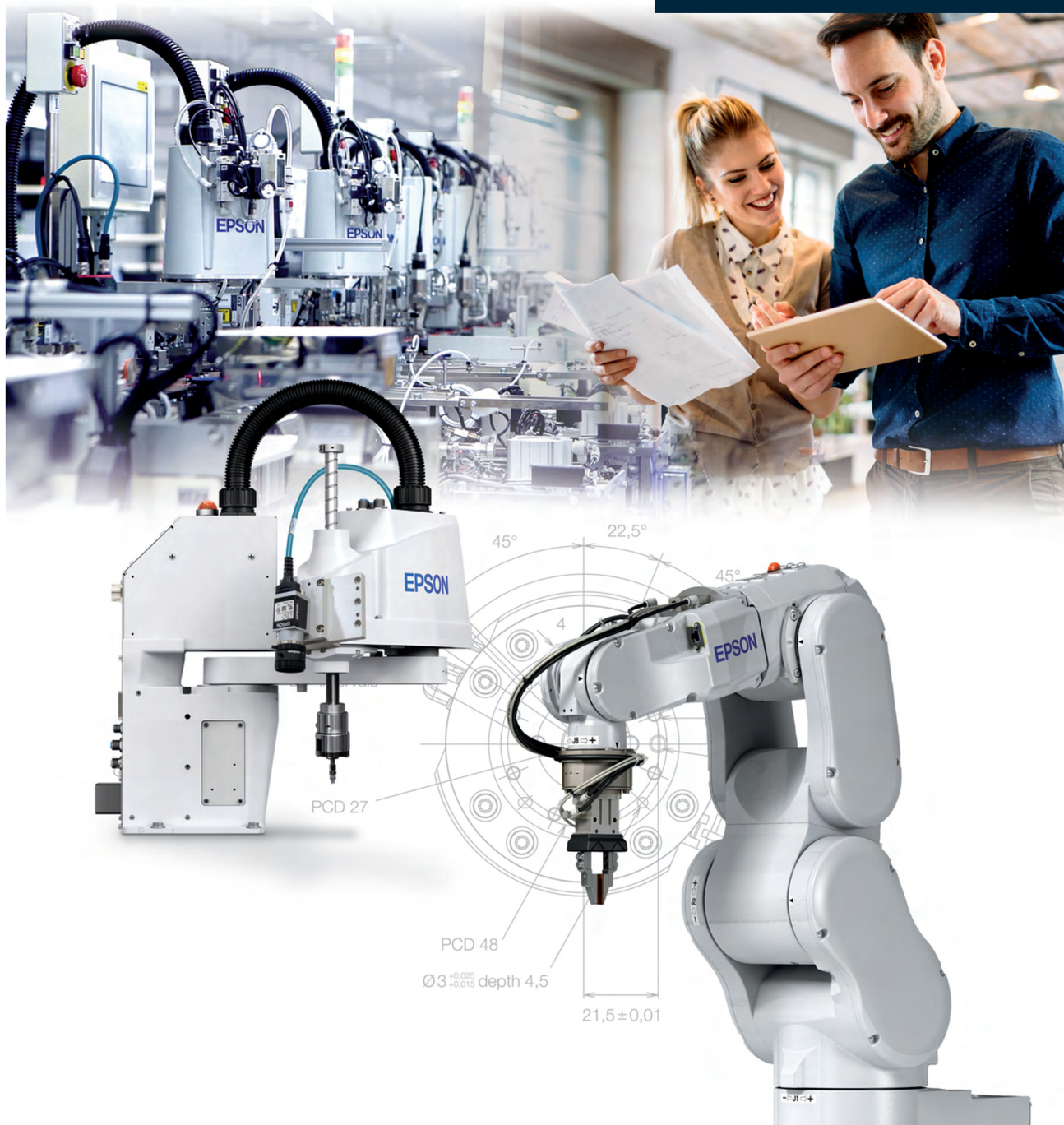
EPSON®

ROBOT SPECIFICATIONS CATALOG



Why Epson® Robots?

As precision automation specialists, the Epson Robots team has been building automation products for nearly four decades. An industry leader in small-parts-assembly applications, we've introduced many firsts. As a result, our innovative products are hard at work in thousands of manufacturing facilities throughout the world.

1 Leading Epson technology

- Epson is the #1 SCARA robot manufacturer in the world
- We introduced the world's first folding-arm 6-Axis robot
- Specialized integrated motion sensors help reduce vibration and increase performance

2 What you need, when you need it

- The Epson lineup features 6-Axis and SCARA robots with payloads up to 20 kg and a reach ranging from 175 mm to 1,480 mm
- We offer a wide range of fully integrated options including vision guidance, conveyor tracking, flexible parts feeding, force guidance and more

3 Intuitive programming software

- Epson RC+® software is extremely user-friendly, making automation setup fast and easy
- It includes time-saving features such as wizards, templates, smart tools and more

4 Reliability you can count on

- Dedicated to helping you find the best solution for your automation needs
- Epson robots are long-lasting and require little maintenance
- Over 150,000 robots sold worldwide

1982	INDUSTRY FIRST 1986	INDUSTRY FIRST 1994	INDUSTRY FIRST 1997	INDUSTRY FIRST 2001	2009	INDUSTRY FIRST 2009	INDUSTRY FIRST 2016	2017	2019	2022
Epson SCARA robots introduced	ISO Class 1 cleanroom robots	Microsoft® Windows® OS support	Compact (under 500 mm reach) SCARA robot introduced PC-based robot controller	Wall/ceiling-mount SCARA robots	Compact, high-speed C3 6-Axis robot	Ceiling-mount RS3 SCARA robot with 360° rotation introduced	N2 6-Axis robot with folding-arm design introduced	Ultra low-cost T3 All-in-One SCARA robot with built-in controller introduced	Ultra low-cost VT6L All-in-One 6-Axis robot with built-in controller introduced	GX-Series high-power-density SCARA robots introduced

INDUSTRY FIRST
Anti-static robots

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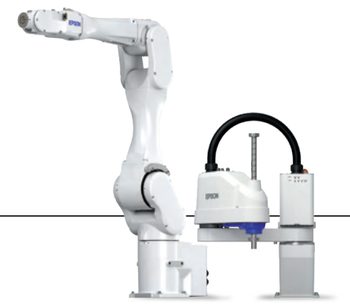

Meet Epson's Lineup of Award-Winning SCARA and 6-Axis Robots

TB-Series

Automate your factory without wasting time or money on complex slide-based solutions. These innovative All-in-One robots are available at an ultra low cost and offer fast, easy integration, taking less time to install than most automation solutions. With reach distances of 400 mm and 600 mm, they can handle payloads of 3 kg and 6 kg.

LSB-Series

The perfect solution for factories looking for maximum value without sacrificing performance, the LSB-Series offers fast, compact performers at a low cost. With reach distances ranging from 400 mm to 1,000 mm, and payloads from 3 kg to 20 kg, they feature cycle times starting at 0.38 sec.

RS-Series

These zero-footprint robots are some of the most unique and flexible SCARA robots available on the market today. With reach distances of 350 mm and 550 mm, and payloads of 3 kg and 4 kg, they offer cycle times starting at 0.34 sec.

VT-Series

Offering next-level technology at an incredible price, VT-Series All-in-One 6-Axis robots ensure easy setup with a built-in controller. With a reach of 900 mm and payloads up to 6 kg, these robots are ideal for simple applications such as machine load/unload, packaging, assembly and more.

C4-Series

C4-Series robots offer excellent performance for the most demanding and complex tasks. Compact yet powerful, they deliver high repeatability and fast cycle times with reach distances ranging from 600 mm to 900 mm and payloads up to 4 kg.

G-/GX-Series

With more than 300 models available, high-performance G- and GX-Series robots are ideal for applications where fast cycle times and high precision are required. The Epson lineup offers reach distances ranging from 175 mm to 1,000 mm and payloads from 1 kg to 20 kg, plus cycle times starting at 0.28 sec.

N-Series

Setting a new standard for 6-Axis robots, the N-Series includes a revolutionary folding-arm design for maximum motion efficiency. N-Series robots offer reach distances of 450 mm to 1,000 mm and payloads of 2.5 kg and 6 kg.

C8-/C12-Series

C8- and C12-Series robots are ideal for demanding applications requiring 6-Axis dexterity. With both long reach and heavy payloads, they provide remarkable flexibility. In fact, these compact robots offer reach distances ranging from 700 mm to 1,400 mm and payloads up to 12 kg.

Industry Solutions

Epson Robots is a leading supplier to a wide variety of manufacturing industries including automotive, medical, electronics, consumer products, industrial and many more. Our customers range from large Fortune 100 companies to small manufacturing facilities.

- **Automotive:** Brakes, clutch components, ignition systems, instrument panels, headlights, mirrors, locks, sensors and more
- **Life sciences:** Contact lenses, glasses, dental instruments, dental implants, hearing aids, pacemakers, blood test systems and much more
- **Electronics:** Chip handling and placement, encoder assembly, board and laser diode testing, wire bonding and more
- **Consumer products:** Smartphones, tablets, speakers, jewelry, watches, cosmetics, printers and more

Global High-Quality Support, When and Where It's Needed

At Epson, our reputation is built on the high quality of our products and services, and maintaining that quality is a worldwide priority. Our support network for robotic products includes nine regional centers, and we stand ready to meet the needs of customers in virtually every major market.

Applications

Epson robots are extremely versatile and provide a wide range of automation possibilities:

- Assembly
- Pick and place
- Material handling
- Packaging
- Kitting/Tray loading
- Machine tending
- Screwdriving
- Dispensing
- Palletizing
- Lab automation
- Inspection and testing
- Finishing
- Grinding

Why Epson SCARA Robots?

Epson's lineup of over 300 models gives users the power to choose the right robot for their application. It's just part of what makes us the #1 SCARA robot manufacturer in the world.

Hundreds of models available

- Sizes ranging from 175 mm to 1,000 mm in reach
- Payloads up to 20 kg
- Tabletop, wall- and ceiling-mount options

Fast speeds

- Extraordinary cycle times to maximize parts per hour

Extreme precision

- Repeatability down to 5 microns

SCARA

TB-Series All-in-One

TB-Series All-in-One SCARA robots are the perfect alternative to complex slide-based solutions. These space-saving robots install in minutes. And, they include the same intuitive software and powerful features found in Epson's high-end robots.

LSB-Series

LSB-Series SCARA robots offer the high performance and great reliability that users have come to expect from Epson, but at a lower cost. LSB-Series SCARAs were created for factories looking for maximum value without giving up performance.

RS-Series

RS-Series robots are some of the most unique and flexible SCARA robots available on the market today. With the ability to cross back under and reach behind themselves, RS-Series robots are able to utilize the entire workspace underneath the arm. As a result, there is no lost space in the center of the work envelope.

G/GX-Series

G- and GX-Series
SCARA robots feature a high-rigidity arm design that delivers high speed, high precision and low vibration. G- and GX-Series SCARA robots offer a wide variety of sizes from 175 mm to 1,000 mm in reach, with up to 20 kg payloads.

Epson is the #1 SCARA robot manufacturer in the world.

TB-SERIES
SCARA ROBOTS

TB-Series All-in-One

Value without compromise

An innovative alternative to complex, slide-based systems, T3-B and T6-B All-in-One SCARA robots feature a built-in controller, power for end-of-arm tooling and 110 V or 220 V power.

T3-B

All-in-One design is the ultimate slide alternative

T6-B

Higher payload and longer reach at an incredible value

ALL IN ONE
BUILT-IN CONTROLLER

TB-SERIES ALL-IN-ONE SPECIFICATIONS

		T3-B	T6-B
Arm length	**Arm #1 + #2**	400 mm	600 mm
Repeatability	**Joints #1, #2**	±0.020 mm	±0.040 mm
Payload	**Rated**	1 kg	2 kg
	Maximum	3 kg	6 kg
Standard cycle time[1]		0.52 sec	0.46 sec
Installation environment		Standard	
Available controllers		Built-in	

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical).

TB-SERIES ALL-IN-ONE SCARA ROBOTS

T3-B

Scan Here for CAD Drawings

The ultimate slide alternative

- Arm length of 400 mm
- Easy to install
- Built-in controller
- Comes standard with 110 V and 220 V power
- No battery required for encoder

SPECIFICATIONS

		T3-B-401
Mounting type		Tabletop
Arm length	Arm #1 + #2	400 mm
Weight (cables not included)		16 kg
Repeatability	Joints #1, #2	±0.020 mm
	Joint #3	±0.020 mm
	Joint #4	±0.020 deg
Max. motion range	Joint #1	±132 deg
	Joint #2	±141 deg
	Joint #3	150 mm
	Joint #4	±360 deg
Payload	Rated	1 kg
	Maximum	3 kg
Standard cycle time[1]		0.52 sec
Joint #4 allowable moment of inertia[2]	Rated	0.003 kg•m^2
	Maximum	0.010 kg•m^2
Joint #3 downward force		83 N
Electric lines		Hand I/O: IN6/OUT4 (D-Sub 15-Pin)/User I/O: IN18/OUT12
Pneumatic lines		Φ6 mm × 2, Φ4 mm × 1
Installation environment		Standard
Available controllers		Built-in
Safety standards		CE Mark: EMC Directive, Machinery Directive, RoHS Directive ANSI/RIA R15.06-2012 NFPA 79 (2007 Edition)

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 1 kg payload (path coordinates optimized for maximum speed).
2 When payload center of gravity is aligned with Joint #4; if not aligned with Joint #4, set parameters using the INERTIA command.

T6-B

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The ultimate slide alternative—with longer reach and higher payload

- Arm length of 600 mm
- Easy to install
- Built-in controller
- Comes standard with 110 V and 220 V power
- No battery required for encoder

SPECIFICATIONS

		T6-B-602
Mounting type		Tabletop
Arm length	Arm #1 + #2	600 mm
Weight (cables not included)		22 kg
Repeatability	Joints #1, #2	±0.040 mm
	Joint #3	±0.020 mm
	Joint #4	±0.020 deg
Max. motion range	Joint #1	±132 deg
	Joint #2	±150 deg
	Joint #3	200 mm
	Joint #4	±360 deg
Payload	Rated	2 kg
	Maximum	6 kg
Standard cycle time[1]		0.46 sec
Joint #4 allowable moment of inertia[2]	Rated	0.010 kg•m^2
	Maximum	0.080 kg•m^2
Joint #3 downward force		83 N
Electric lines		Hand I/O: IN6/OUT4 (D-Sub 15-Pin)/User I/O: IN18/OUT12
Pneumatic lines		Φ6 mm × 2, Φ4 mm × 1
Installation environment		Standard
Available controllers		Built-in
Safety standards		CE Mark: EMC Directive, Machinery Directive, RoHS Directive ANSI/RIA R15.06-2012 NFPA 79 (2007 Edition)

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 2 kg payload (path coordinates optimized for maximum speed).
2 When payload center of gravity is aligned with Joint #4; if not aligned with Joint #4, set parameters using the INERTIA command.

LSB-Series

These fast, compact, low-cost solutions are ideal for factories looking for maximum value without sacrificing performance. With payloads ranging from 3 kg to 20 kg and cycle times starting at 0.38 seconds, LSB-Series SCARA robots offer a variety of opportunities for manufacturers searching for a reduced-cost, high-performance automation solution with great reliability.

LSB-SERIES
SCARA ROBOTS

LS3-B

Fast, compact and low cost

LS6-B

Great performance at an affordable price

LS10-B

Powerful performance and a large payload at an affordable value

LS20-B

Remarkable value with long reach, high performance and heavy payload

LSB-SERIES SPECIFICATIONS

		LS3-B	LS6-B	LS10-B	LS20-B
Arm length	**Arm #1 + #2**	400 mm	500/600/700 mm	600/700/800 mm	800/1,000 mm
Repeatability	**Joints #1, #2**	±0.010 mm	±0.020 mm	±0.020/±0.020/ ±0.025 mm	±0.025 mm
Payload	**Rated**	1 kg	2 kg	5 kg	10 kg
	Maximum	3 kg	6 kg	10 kg	20 kg
Standard cycle time[1]		0.42 sec	0.38/0.39/0.42 sec	0.39/0.41/0.44 sec	0.39/0.43 sec
Installation environments		Standard/Cleanroom ISO Class 4			
Available controllers		RC90B			

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical).

LSB-SERIES SCARA ROBOTS

LS3-B

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Fast, compact and low-cost

- Arm length of 400 mm
- Small footprint
- Built-in camera cable
- Cleanroom ISO Class 4 models available

SPECIFICATIONS

		LS3-B401
Mounting type		Tabletop
Arm length	**Arm #1 + #2**	400 mm
Weight (cables not included)		14 kg
Repeatability	**Joints #1, #2**	±0.010 mm
	Joint #3	±0.010 mm
	Joint #4	±0.010 deg
Max. motion range	**Joint #1**	±132 deg
	Joint #2	±141 deg
	Joint #3 Std	150 mm
	Joint #3 Clean	120 mm
	Joint #4	±360 deg
Payload	**Rated**	1 kg
	Maximum	3 kg
Standard cycle time[1]		0.42 sec
Joint #4 allowable	**Rated**	0.005 kg•m^2
moment of inertia[2]	**Maximum**	0.050 kg•m^2
Joint #3 downward force		100 N
Electric lines		15 (15-Pin: D-Sub), 8 (8-Pin: RJ45) Cat5e
Pneumatic lines		Φ4 mm × 1, Φ6 mm × 2
Installation environments		Standard/Cleanroom ISO Class 4
Available controllers		RC90B
Safety standards		CE Mark: EMC Directive, Machinery Directive, RoHS Directive ANSI/RIA R15.06-2012 NFPA 79 (2007 Edition)

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 2 kg payload (path coordinates optimized for maximum speed).
2 When payload center of gravity is aligned with Joint #4; if not aligned with Joint #4, set parameters using the INERTIA command.

LS6-B

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Low cost and high performance

- Arm lengths of 500, 600 and 700 mm
- Built-in camera cable
- Fast cycle throughput
- Cleanroom ISO Class 4 models available

SPECIFICATIONS

		LS6-B502	LS6-B602	LS6-B702
Mounting type		Tabletop		
Arm length	**Arm #1 + #2**	500 mm	600 mm	700 mm
Weight (cables not included)		17 kg	17 kg	18 kg
Repeatability	**Joints #1, #2**	±0.020 mm		
	Joint #3	±0.010 mm		
	Joint #4	±0.010 deg		
Max. motion range	**Joint #1**	±132 deg		
	Joint #2	±150 deg		
	Joint #3 Std	200 mm		
	Joint #3 Clean	170 mm		
	Joint #4	±360 deg		
Payload	**Rated**	2 kg		
	Maximum	6 kg		
Standard cycle time[1]		0.38 sec	0.39 sec	0.42 sec
Joint #4 allowable	**Rated**	0.010 kg•m^2		
moment of inertia[2]	**Maximum**	0.120 kg•m^2		
Joint #3 downward force		100 N		
Electric lines		15 (15-Pin: D-Sub), 8 (8-Pin: RJ45) Cat5e		
Pneumatic lines		Φ4 mm × 1, Φ6 mm × 2		
Installation environments		Standard/Cleanroom ISO Class 4		
Available controllers		RC90B		
Safety standards		CE Mark: EMC Directive, Machinery Directive, RoHS Directive ANSI/RIA R15.06-2012 NFPA 79 (2007 Edition)		

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 2 kg payload (path coordinates optimized for maximum speed).
2 When payload center of gravity is aligned with Joint #4; if not aligned with Joint #4, set parameters using the INERTIA command.

LSB-SERIES SCARA ROBOTS

LS10-B

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Powerful, fast and affordable

- Arm lengths of 600, 700 and 800 mm
- Built-in camera cable
- No battery required for encoder
- Cleanroom ISO Class 4 models available

SPECIFICATIONS

		LS10-B60X	LS10-B70X	LS10-B80X
Mounting type		Tabletop		
Arm length	**Arm #1 + #2**	600 mm	700 mm	800 mm
Weight (cables not included)		22 kg	22 kg	23 kg
Repeatability	**Joints #1, #2**	±0.020 mm	±0.020 mm	±0.025 mm
	Joint #3	±0.010 mm		
	Joint #4	±0.010 deg		
Max. motion range	**Joint #1**	±132 deg		
	Joint #2	±150 deg		
	Joint #3 Std	200 mm or 300 mm		
	Joint #3 Clean	170 mm or 270 mm		
	Joint #4	±360 deg		
Payload	**Rated**	5 kg		
	Maximum	10 kg		
Standard cycle time[1]		0.39 sec	0.41 sec	0.44 sec
Joint #4 allowable moment of inertia[2]	**Rated**	0.020 kg•m^2		
	Maximum	0.300 kg•m^2		
Joint #3 downward force		200 N		
Electric lines		15 (15-Pin: D-Sub), 8 (8-Pin: RJ45) Cat5e		
Pneumatic lines		Φ4 mm × 1, Φ6 mm × 2		
Installation environments		Standard/Cleanroom ISO Class 4		
Available controllers		RC90B		
Safety standards		CE Mark: EMC Directive, Machinery Directive, RoHS Directive ANSI/RIA R15.06-2012 NFPA 79 (2007 Edition)		

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 2 kg payload (path coordinates optimized for maximum speed).
2 If the center of gravity is at the center of each arm. If the center of gravity is not at the center of each arm, set the eccentric quantity using the INERTIA command.

LS20-B

Scan Here for CAD Drawings

Long reach, heavy payload— all at a great value

- Arm lengths of 800 and 1,000 mm
- Fast cycle times
- Built-in camera cable
- Cleanroom ISO Class 4 models available

SPECIFICATIONS

		LS20-B804	LS20-BA04
Mounting type		Tabletop	
Arm length	**Arm #1 + #2**	800 mm	1,000 mm
Weight (cables not included)		48 kg	51 kg
Repeatability	**Joints #1, #2**	±0.025 mm	
	Joint #3	±0.010 mm	
	Joint #4	±0.010 deg	
Max. motion range	**Joint #1**	±132 deg	
	Joint #2	±152 deg	
	Joint #3 Std	420 mm	
	Joint #3 Clean	390 mm	
	Joint #4	±360 deg	
Payload	**Rated**	10 kg	
	Maximum	20 kg	
Standard cycle time[1]		0.39 sec	0.43 sec
Joint #4 allowable moment of inertia[2]	**Rated**	0.050 kg•m^2	
	Maximum	1.000 kg•m^2	
Joint #3 downward force		250 N	
Electric lines		15 (15-Pin: D-Sub), 9 (9-Pin: D-Sub), 8 (8-Pin: RJ45) Cat5e	
Pneumatic lines		Φ4 mm × 1, Φ6 mm × 2	
Installation environments		Standard/Cleanroom ISO Class 4	
Available controllers		RC90B	
Safety standards		CE Mark: EMC Directive, Machinery Directive, RoHS Directive ANSI/RIA R15.06-2012 NFPA 79 (2007 Edition)	

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 2 kg payload (path coordinates optimized for maximum speed).
2 When payload center of gravity is aligned with Joint #4; if not aligned with Joint #4, set parameters using the INERTIA command.

RS-Series

RS-Series SCARA robots are unique and highly flexible. Offering payloads of 3 kg or 4 kg and cycle times starting at 0.34 seconds, they have the ability to cross under as well as reach behind themselves. RS-Series robots are able to utilize the entire workspace underneath the arm. As a result, there is no lost space in the center of the work envelope.

RS-SERIES
SCARA ROBOTS

RS3

Compact SCARA robot with unique workspace design

RS4

High-performance, innovative workspace design with longer reach capabilities

RS-SERIES SPECIFICATIONS

		RS3	RS4
Arm length	**Arm #1 + #2**	350 mm	550 mm
Repeatability	**Joints #1, #2**	±0.010 mm	±0.015 mm
Payload	**Rated**	1 kg	1 kg
	Maximum	3 kg	4 kg
Standard cycle time[1]		0.34 sec	0.39 sec
Installation environments		Standard/Cleanroom ISO Class 3 with ESD	
Available controllers		RC700A	

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical).

RS3

Scan Here for CAD Drawings

Compact with unique workspace design

- Arm length of 350 mm
- Payloads up to 3 kg
- Maximum motion efficiency
- Cleanroom ISO Class 3 models available

SPECIFICATIONS

		RS3-351
Mounting type		Ceiling
Arm length	**Arm #1 + #2**	350 mm
Weight (cables not included)		17 kg
Repeatability	**Joints #1, #2**	±0.010 mm
	Joint #3	±0.010 mm
	Joint #4	±0.010 deg
Max. motion range	**Joint #1**	±225 deg
	Joint #2	±225 deg
	Joint #3 Std	130 mm
	Joint #3 Clean	100 mm
	Joint #4	±720 deg
Payload	**Rated**	1 kg
	Maximum	3 kg
Standard cycle time[1]		0.34 sec
Joint #4 allowable moment of inertia[2]	**Rated**	0.005 kg•m²
	Maximum	0.050 kg•m²
Joint #3 downward force		150 N
Electric lines		15-Pin (D-Sub)
Pneumatic lines		Φ4 mm × 1, Φ6 mm × 2
Installation environments		Standard/Cleanroom ISO Class 3 with ESD
Available controllers		RC700A
Safety standards		CE Mark: EMC Directive, Machinery Directive, RoHS Directive UL1740 ANSI/RIA R15.06 NFPA 79

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 1 kg payload (path coordinates optimized for maximum speed).
2 When payload center of gravity is aligned with Joint #4; if not aligned with Joint #4, set parameters using the INERTIA command.

RS4

Scan Here for CAD Drawings

High-performance, innovative workspace design

- Arm length of 550 mm
- Payloads up to 4 kg
- Superior cycle times
- Cleanroom ISO Class 3 models available

SPECIFICATIONS

		RS4-551
Mounting type		Ceiling
Arm length	**Arm #1 + #2**	550 mm
Weight (cables not included)		19 kg
Repeatability	**Joints #1, #2**	±0.015 mm
	Joint #3	±0.010 mm
	Joint #4	±0.010 deg
Max. motion range	**Joint #1**	±225 deg
	Joint #2	±225 deg
	Joint #3 Std	130 mm
	Joint #3 Clean	100 mm
	Joint #4	±720 deg
Payload	**Rated**	1 kg
	Maximum	4 kg
Standard cycle time[1]		0.39 sec
Joint #4 allowable moment of inertia[2]	**Rated**	0.005 kg•m²
	Maximum	0.050 kg•m²
Joint #3 downward force		150 N
Electric lines		15-Pin (D-Sub)
Pneumatic lines		Φ4 mm × 1, Φ6 mm × 2
Installation environments		Standard/Cleanroom ISO Class 3 with ESD
Available controllers		RC700A
Safety standards		CE Mark: EMC Directive, Machinery Directive, RoHS Directive UL1740 ANSI/RIA R15.06 NFPA 79

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 1 kg payload (path coordinates optimized for maximum speed).
2 When payload center of gravity is aligned with Joint #4; if not aligned with Joint #4, set parameters using the INERTIA command.

GX-SERIES
SCARA ROBOTS

GX-Series

Introducing the GX-Series, part of Epson's new high-power-density SCARA robot lineup. The GX-Series builds upon 40 years of expertise to deliver next-level performance and flexibility in a compact footprint. A breakthrough in productivity, the GX-Series uses advanced GYROPLUS™ Technology to provide fast production speeds and smooth motion control, all with higher payloads.

GX4

Ultra high performance and flexibility

GX8

Heavier payloads and longer reach with reduced vibration

GX8 SCARA

GX-SERIES SPECIFICATIONS

		GX4	GX8
Arm length	**Arm #1 + #2**	250/300/350 mm	450/550/650 mm
Repeatability	**Joints #1, #2**	±0.008/ ±0.010 mm	±0.015 mm
Payload	**Rated**	2 kg	4 kg
	Maximum	4 kg	8 kg
Standard cycle time		0.33/0.34/0.35 sec	0.28/0.30/0.33 sec
Installation environments		Standard/ESD/Cleanroom ISO Class 3 with ESD	Standard/ESD/Cleanroom ISO Class 3 with ESD/Protected IP65
Available controllers		RC700D	

GX-SERIES SCARA ROBOTS

GX4

Scan Here for CAD Drawings

Ultra high performance and flexibility

- Handles high payloads from a small footprint
- Arm lengths of 250, 300 and 350 mm
- GYROPLUS Technology reduces vibration
- Curved arm option (350 mm) maximizes work envelope
- Cleanroom ISO Class 3 models available

SPECIFICATIONS

			GX4-A251x	GX4-A301x		GX4-A351x	
Mounting type			Tabletop	Tabletop	Multiple	Tabletop	Multiple
Arm length		**Arm #1 + #2**	250 mm	300 mm		350 mm	
Weight (cables not included)			15 kg	15 kg	17 kg	16 kg	17 kg
Repeatability		**Joints #1, #2**	±0.008 mm	±0.010 mm			
		Joint #3	±0.010 mm				
		Joint #4	±0.005 deg				
Max. motion range	**Straight**	**Joint #1**	±140 deg	±140 deg	±115 deg	±140 deg	±120 deg
		Joint #2 Std	±141 deg	±142 deg	±135 deg	±142 deg	
		Joint #2 Clean	±137 deg	±137 deg	±135 deg	±142 deg	
	Curved	**Joint #1 Right Hand**				-110 ~ 165 deg	-
		Joint #1 Left Hand				-165 ~ 110 deg	
		Joint #2 Right Hand Std & ESD				-120 ~ 165 deg	
		Joint #2 Right Hand Clean				-120 ~ 160 deg	
		Joint #2 Left Hand Std & ESD				-165 ~ 120 deg	
		Joint #2 Left Hand Clean				-160 ~ 120 deg	
	All Models	**Joint #3 Std & ESD**	150 mm				
		Joint #3 Clean	120 mm				
		Joint #4	±360 deg				
Payload		**Rated**	2 kg				
		Maximum	4 kg				
Standard cycle time[1]			0.33 sec	0.34 sec		0.35 sec	
Joint #4 allowable moment of inertia[2]		**Rated**	0.005 kg•m²				
		Maximum	0.05 kg•m²				
Joint #3 downward force			150 N				
Electric lines			15-Pin (D-Sub), 8-Pin (RJ45 Cat5e)				
Pneumatic lines			Φ6 mm x 2, ø4 mm x 1				
Installation environments			Standard/ESD/Cleanroom ISO Class 3 with ESD				
Available controllers			RC700D				
Safety standards			CE Mark: UL1740				

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 2 kg payload of tabletop model boost mode (path coordinates optimized for maximum speed).
2 When payload center of gravity is aligned with Joint #4; if not aligned with Joint #4, set parameters using the INERTIA command.

GX8

Scan Here for CAD Drawings

Heavier payloads and longer reach with reduced vibration

- High power density
- Arm lengths of 450, 550 and 650 mm
- Longer Z axis available on all models
- Higher acceleration and faster settling times
- Cleanroom ISO Class 3 models available

SPECIFICATIONS

		GX8-A45x			GX8-A55x			GX8-A65x		
Mounting type		Tabletop	Ceiling	Wall	Tabletop	Ceiling	Wall	Tabletop	Ceiling	Wall
Arm length	**Arm #1 + #2**	450 mm			550 mm			650 mm		
Weight (cables not included)		33 kg		35 kg	34 kg		36 kg	35 kg		37 kg
Repeatability	**Joints #1, #2**	±0.015 mm								
	Joint #3	±0.010 mm								
	Joint #4	±0.005 deg								
Max. motion range	**Joint #1**	±152 deg	±105 deg	±105 deg	±152 deg	±152 deg	±135 deg	±152 deg	±152 deg	±148 deg
	Joint #2 Std & ESD	Z: 0 mm ~ -270 mm ± 147.5 deg Z: -270 mm ~ -330 mm ± 145 deg	±125 deg		±147.5 deg			±147.5 deg		
	Joint #2 Clean/ Protected	Z: 0 mm ~ -240 mm ± 147.5 deg Z: -240 mm ~ -300 mm ± 137.5 deg			Z: 0 ~ -240 mm ± 147.5 deg, Z: -240 ~ -300 mm ± 145 deg		±145 deg			
	Joint #3 Std & ESD	200 mm/330 mm								
	Joint #3 Clean/ Protected	170 mm/300 mm								
	Joint #4	±360 deg								
Payload	**Rated**	4 kg								
	Maximum	8 kg								
Standard cycle time[1]		0.28 sec			0.30 sec			0.33 sec		
Joint #4 allowable moment of inertia[2]	**Rated**	0.01 kg•m²								
	Maximum	0.16 kg•m²								
Joint #3 downward force		150 N								
Electric lines		15-Pin (D-Sub), 9-Pin (D-Sub), 8-Pin (RJ45 Cat5e)								
Pneumatic lines		Φ4 mm x 2, Φ6 mm x 2								
Installation environments		Standard/ESD/Cleanroom ISO Class 3 with ESD/Protected IP65								
Available controllers		RC700D								
Safety standards		CE Mark: UL1740								

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 2 kg payload of tabletop model boost mode (path coordinates optimized for maximum speed).
2 When payload center of gravity is aligned with Joint #4; if not aligned with Joint #4, set parameters using the INERTIA command.

G-Series

With a vast product lineup including reach options from 175 mm to 1,000 mm, G-Series robots are rich in features and performance. With payloads ranging from 1 kg to 20 kg and cycle times down to 0.29 seconds, G-Series robots offer the speed and overall performance to accomplish even the most difficult tasks. Featuring a unique high-rigidity arm design, which reduces vibration, these robots deliver fast speeds and high precision with no overshoot or ringing.

G-SERIES
SCARA ROBOTS

G1

High-performance, high-precision mini SCARA robot

G3

Compact, fast and powerful with straight or unique curved arm

G6

Ultra fast speeds with extraordinary motion range

G10

Provides high speed at heavy payloads

G20

Long reach and high payloads with strong J4 inertia

Cleanroom/ESD G6 SCARA

G-SERIES SPECIFICATIONS

		G1	G3	G6	G10	G20
Arm length	**Arm #1 + #2**	175/225 mm	250/300/350 mm	450/550/650 mm	650/850 mm	850/1,000 mm
Repeatability	**Joints #1, #2**	±0.005/ ±0.008 mm	±0.008/ ±0.010 mm	±0.015 mm	±0.025 mm	±0.025 mm
Payload	**Rated**	0.5 kg	1 kg	3 kg	5 kg	10 kg
	Maximum	1 kg	3 kg	6 kg	10 kg	20 kg
Standard cycle time[1]		0.29/0.30 sec	0.36/0.37/0.37 sec	0.33/0.36/0.38 sec	0.34/0.37 sec	0.37/0.42 sec
Installation environments		Standard/Cleanroom ISO Class 3 with ESD		Standard/Cleanroom ISO Class 3 with ESD/Protected IP54 and IP65		
Available controllers		RC700A				

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical; G1: 100 mm horizontal, 25 mm vertical).

G-SERIES SCARA ROBOTS

G1

Scan Here for CAD Drawings

Powerful mini SCARA

- High-precision repeatabilities down to 0.005 mm
- Arm lengths of 175 and 225 mm
- Ultra compact, yet extremely powerful
- Cleanroom ISO Class 3 models available
- 3-Axis models available

SPECIFICATIONS

		G1-171		G1-221		G1-171xZ		G1-221xZ	
Number of axes		4-Axis				3-Axis			
Mounting type		Tabletop				Tabletop			
Arm length	Arm #1 + #2	175 mm		225 mm		175 mm		225 mm	
Weight (cables not included)		8 kg				8 kg			
Repeatability	Joints #1, #2	±0.005 mm		±0.008 mm		±0.005 mm		±0.008 mm	
	Joint #3	±0.010 mm				±0.010 mm			
	Joint #4	±0.010 deg				–			
Max. motion range	Joint #1	±125 deg				±125 deg			
	Joint #2 Std	±140 deg		±152 deg		±135 deg		±135 deg	
	Joint #2 Clean	±140 deg		±149 deg		±123 deg		±132 deg	
	Joint #3 Std	100 mm				100 mm			
	Joint #3 Clean	80 mm				80 mm			
	Joint #4	±360 deg				–			
Payload	Rated	0.5 kg				0.5 kg			
	Maximum	1 kg				1.5 kg			
Standard cycle time[1]		0.29 sec		0.30 sec		0.29 sec		0.30 sec	
Joint #4 allowable moment of inertia[2]	Rated	0.0003 kg•m²				–			
	Maximum	0.0040 kg•m²				–			
Joint #3 downward force		50 N							
Electric lines		24 (9-Pin D-Sub, 15-Pin D-Sub)							
Pneumatic lines		Φ4 mm × 1, Φ6 mm × 2							
Installation environments		Standard/Cleanroom ISO Class 3 with ESD							
Available controllers		RC700A							
Safety standards		CE Mark: EMC Directive, Machinery Directive, RoHS Directive UL1740 ANSI/RIA R15.06 NFPA 79							

1 Cycle time based on round-trip arch motion (100 mm horizontal, 25 mm vertical) with 0.5 kg payload (path coordinates optimized for maximum speed).
2 When payload center of gravity is aligned with Joint #4; if not aligned with Joint #4, set parameters using the INERTIA command.

G3

Scan Here for CAD Drawings

Compact and ultra powerful

- Arm lengths of 250, 300 and 350 mm
- Handles payloads up to 3 kg
- Fast cycle times for increased productivity
- Available with straight or curved arm
- Cleanroom ISO Class 3 models available

SPECIFICATIONS

			G3-251	G3-301		G3-351	
Mounting type			Tabletop	Tabletop	Multiple	Tabletop	Multiple
Arm length		Arm #1 + #2	250 mm	300 mm		350 mm	
Weight (cables not included)			14 kg				
Repeatability		Joints #1, #2	±0.008 mm	±0.010 mm			
		Joint #3	±0.010 mm				
		Joint #4	±0.005 deg				
Max. motion range	Straight	Joint #1	±140 deg	±140 deg	±115 deg	±140 deg	±120 deg
		Joint #2 Std	±141 deg	±142 deg	±135 deg	±142 deg	
		Joint #2 Clean	±137 deg	±141 deg	±135 deg	±142 deg	
	Curved	Joint #1 Right Hand	–	-125~150 deg	–	-110~165 deg	-105~130 deg
		Joint #1 Left Hand	–	-150~125 deg	–	-165~110 deg	-130~105 deg
		Joint #2 Right Hand Std	–	-135~150 deg	–	-120~165 deg	-120~160 deg
		Joint #2 Right Hand Clean		-135~145 deg		-120~160 deg	-120~150 deg
		Joint #2 Left Hand Std	–	-150~135 deg	–	-165~120 deg	-160~120 deg
		Joint #2 Left Hand Clean		-145~135 deg		-160~120 deg	-150~120 deg
	All models	Joint #3 Std	150 mm				
		Joint #3 Clean	120 mm				
		Joint #4	±360 deg				
Payload		Rated	1 kg				
		Maximum	3 kg				
Standard cycle time[1]			0.36 sec	0.37 sec			
Joint #4 allowable moment of inertia[2]		Rated	0.005 kg•m²				
		Maximum	0.050 kg•m²				
Joint #3 downward force			150 N				
Electric lines			15-Pin (D-Sub)				
Pneumatic lines			Φ4 mm × 1, Φ6 mm × 2				
Installation environments			Standard/Cleanroom ISO Class 3 with ESD				
Available controllers			RC700A				
Safety standards			CE Mark: EMC Directive, Machinery Directive, RoHS Directive ANSI/RIA R15.06 UL1740 NFPA 79				

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 1 kg payload (path coordinates optimized for maximum speed).
2 When payload center of gravity is aligned with Joint #4; if not aligned with Joint #4, set parameters using the INERTIA command.

G-SERIES SCARA ROBOTS

G6

Scan Here for CAD Drawings

Compact, fast and powerful

- Arm lengths of 450, 550 and 650 mm
- High-rigidity arm = ultra high speed
- Tabletop, wall- and ceiling-mount models available
- Cleanroom ISO Class 3 and Protected IP65 models available

SPECIFICATIONS

		G6-45x			G6-55x			G6-65x		
Mounting type		Tabletop	Ceiling	Wall	Tabletop	Ceiling	Wall	Tabletop	Ceiling	Wall
Arm length	**Arm #1 + #2**	450 mm			550 mm			650 mm		
Weight (cables not included)		27 kg		29 kg	27 kg		29 kg	28 kg		29.5 kg
Repeatability	**Joints #1, #2**	±0.015 mm								
	Joint #3	±0.010 mm								
	Joint #4	±0.005 deg								
Max. motion range	**Joint #1**	±152 deg	±120 deg	±105 deg	±152 deg		±135 deg	±152 deg		±148 deg
	Joint #2	Z: 0 mm ~ -270 mm ±147.5 deg Z: -270 mm ~ -330 mm ±145 deg	±130 deg		±147.5 deg					
	Joint #3 Std	180 mm/330 mm								
	Joint #3 Clean	150 mm/300 mm								
	Joint #4	±360 deg								
Payload	**Rated**	3 kg								
	Maximum	6 kg								
Standard cycle time[1]		0.33 sec			0.36 sec			0.38 sec		
Joint #4 allowable moment of inertia[2]	**Rated**	0.010 kg•m^2								
	Maximum	0.120 kg•m^2								
Joint #3 downward force		150 N								
Electric lines		24 (9-Pin D-Sub, 15-Pin D-Sub)								
Pneumatic lines		Φ4 mm × 2, Φ6 mm × 2								
Installation environments		Standard/Cleanroom ISO Class 3 with ESD/Protected IP54 and IP65								
Available controllers		RC700A								
Safety standards		CE Mark: EMC Directive, Machinery Directive, RoHS Directive UL1740 ANSI/RIA R15.06 NFPA 79								

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 1 kg payload (path coordinates optimized for maximum speed).
2 When payload center of gravity is aligned with Joint #4; if not aligned with Joint #4, set parameters using the INERTIA command.

G-SERIES SCARA ROBOTS

G10

Scan Here for CAD Drawings

Long reach at high speeds

- Arm lengths of 650 and 850 mm
- Reduced residual vibration for faster accel./decel. rates
- Tabletop, wall- and ceiling-mount models available
- Cleanroom ISO Class 3 and Protected IP65 models available

SPECIFICATIONS

		G10-65x			G10-85x		
Mounting type		Tabletop	Ceiling	Wall	Tabletop	Ceiling	Wall
Arm length	**Arm #1 + #2**	650 mm			850 mm		
Weight (cables not included)		46 kg		51 kg	48 kg		53 kg
Repeatability	**Joints #1, #2**	±0.025 mm					
	Joint #3	±0.010 mm					
	Joint #4	±0.005 deg					
Max. motion range	**Joint #1**	±152 deg	±107 deg		±152 deg		±107 deg
	Joint #2	±152.5 deg	±130 deg		For Clean/Protected models ±152.5 deg below Z = -360 ~ -390 deg ±151 deg		
	Joint #3 Std	180 mm/420 mm					
	Joint #3 Clean	150 mm/390 mm					
	Joint #4	±360 deg					
Payload	**Rated**	5 kg					
	Maximum	10 kg					
Standard cycle time[1]		0.34 sec			0.37 sec		
Joint #4 allowable moment of inertia[2]	**Rated**	0.020 kg•m²					
	Maximum	0.250 kg•m²					
Joint #3 downward force		250 N					
Electric lines		24 (9-Pin D-Sub, 15-Pin D-Sub)					
Pneumatic lines		Φ4 mm × 2, Φ6 mm × 2					
Installation environments		Standard/Cleanroom ISO Class 3 with ESD/Protected IP54 and IP65					
Available controllers		RC700A					
Safety standards		CE Mark: EMC Directive, Machinery Directive, RoHS Directive UL1740 ANSI/RIA R15.06 NFPA 79					

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 2 kg payload (path coordinates optimized for maximum speed).
2 When payload center of gravity is aligned with Joint #4; if not aligned with Joint #4, set parameters using the INERTIA command.

G20

Scan Here for CAD Drawings

Ultra long reach and heavy payload

- Arm lengths of 850 and 1,000 mm
- Unique design structure for high rigidity
- Tabletop, wall- and ceiling-mount models available
- Cleanroom ISO Class 3 and Protected IP65 models available

SPECIFICATIONS

		G20-85x			G20-A0x		
Mounting type		Tabletop	Ceiling	Wall	Tabletop	Ceiling	Wall
Arm length	**Arm #1 + #2**	850 mm			1,000 mm		
Weight (cables not included)		48 kg		53 kg	50 kg		55 kg
Repeatability	**Joints #1, #2**	±0.025 mm					
	Joint #3	±0.010 mm					
	Joint #4	±0.005 deg					
Max. motion range	**Joint #1**	±152 deg	±107 deg		±152 deg		±107 deg
	Joint #2	±152.5 deg	±130 deg		For Clean/Protected models ±152.5 deg below Z = -360 ~ -390 deg ±151 deg		
	Joint #3 Std	180 mm/420 mm					
	Joint #3 Clean	150 mm/390 mm					
	Joint #4	±360 deg					
Payload	**Rated**	10 kg					
	Maximum	20 kg					
Standard cycle time[1]		0.37 sec			0.42 sec		
Joint #4 allowable moment of inertia[2]	**Rated**	0.050 kg•m²					
	Maximum	0.450 kg•m²					
Joint #3 downward force		250 N					
Electric lines		24 (9-Pin D-Sub, 15-Pin D-Sub)					
Pneumatic lines		Φ4 mm × 2, Φ6 mm × 2					
Installation environments		Standard/Cleanroom ISO Class 3 with ESD/Protected IP54 and IP65					
Available controllers		RC700A					
Safety standards		CE Mark: EMC Directive, Machinery Directive, RoHS Directive UL1740 ANSI/RIA R15.06 NFPA 79					

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 2 kg payload (path coordinates optimized for maximum speed).
2 When payload center of gravity is aligned with Joint #4; if not aligned with Joint #4, set parameters using the INERTIA command.

Why Epson 6-Axis Robots?

Epson's space-saving 6-Axis robots enable a remarkable range of motion to maximize application possibilities.

World's first folding-arm design

- Epson's innovative N-Series offers significant advantages in motion and workspace efficiency

Proven technology

- Epson 6-Axis robots utilize the same controls, software and motion technologies found in our industry-leading SCARA robots

SlimLine design

- Saves valuable factory floor space and allows our robots to fit where other robots can't—without compromising power, speed or reach
- Compact wrist pitch enables our robots to access hard-to-reach places in confined spaces

6-AXIS

VT-Series All-in-One

VT-Series All-in-One 6-Axis robots feature great performance at an ultra low price, offering many of the same features as Epson high-end robots. VT-Series robots include a built-in controller and simplified cabling, allowing fast, easy integration.

N-Series

The **N-Series** lineup features a revolutionary compact folding-arm design that maximizes motion efficiency for faster cycle times. Packed with unique technology, the N-Series significantly reduces workspace requirements when compared to typical 6-Axis robots.

C-Series

C-Series 6-Axis robots provide great cycle times and a unique SlimLine design, backed by remarkable precision and motion range. These compact robots offer exceptional performance for even the most demanding and complex applications.

VT-SERIES

6-AXIS ROBOTS

ALL IN ONE
BUILT-IN CONTROLLER

VT-Series All-in-One

With a built-in controller and simplified cabling, VT-Series All-in-One 6-Axis robots offer quick setup and installation. Featuring 110 V and 220 V power connections or a DC-powered version, they ensure easy integration—whether in a lab, an industrial environment or a mobile application.

VT6L

A feature-packed performer at a remarkably low cost

VT-SERIES ALL-IN-ONE SPECIFICATIONS

		VT6L
Arm length		920 mm
Repeatability	**Joints #1 – #6**	±0.100 mm
Payload	**Rated**	3 kg
	Maximum	6 kg
Standard cycle time[1]		0.60 sec
Installation environments		Standard/Cleanroom ISO Class 4/Protected IP67
Available controllers		Built-in

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical).

VT6L

Scan Here for CAD Drawings

Full-featured, ultra low cost

- Arm length of 900 mm
- Payloads up to 6 kg
- Built-in controller
- Available with 110 V and 220 V power or as a DC-powered version

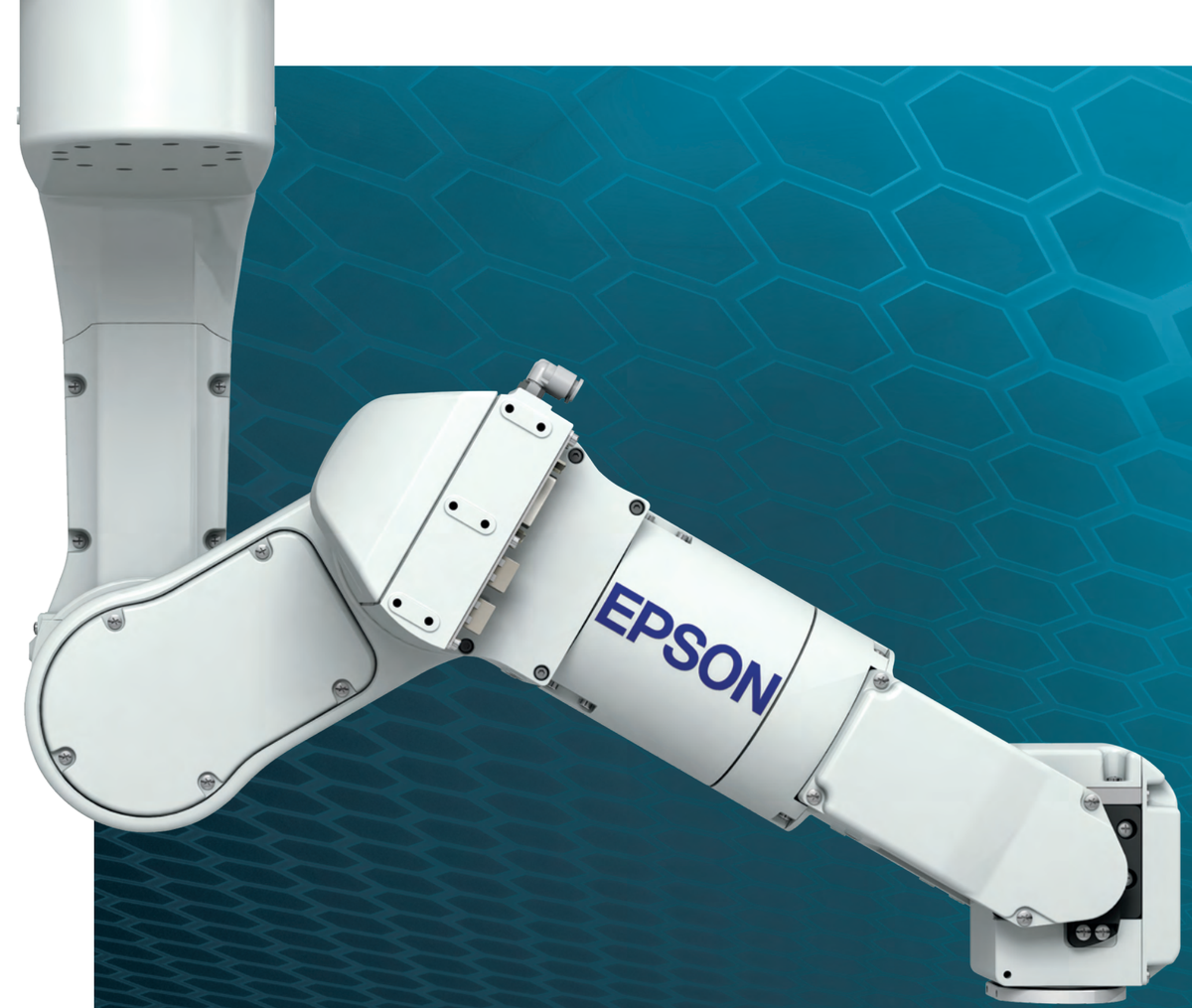
SPECIFICATIONS

		VT6-A901 (VT6L)			VT6-A901-DC (VT6L-DC)
Mounting type		Tabletop	Ceiling	Wall	Tabletop
Degree of freedom		6			6
Arm length	**P Point: through the center of J4/J5/J6**	920 mm			920 mm
Wrist flange surface		1,000 mm			1,000 mm
Weight (cables not included)		40 kg			40 kg
Repeatability	**Joints #1 – #6**	±0.100 mm			±0.100 mm
Max. motion range	**Joint #1**	±170 deg/±170 deg/±30 deg			±170 deg/±170 deg/±30 deg
	Joint #2	-160 ~ +65 deg (225 deg)			-160 ~ +65 deg (225 deg)
	Joint #3	-51 ~ +190 deg (241 deg)			-51 ~ +190 deg (241 deg)
	Joint #4	±200 deg			±200 deg
	Joint #5	±125 deg			±125 deg
	Joint #6	±360 deg			±360 deg
Payload	**Rated**	3 kg			3 kg
	Maximum	6 kg			6 kg
Standard cycle time[1]		0.60 sec			0.60 sec
Allowable moment of inertia[2]	**Joint #4**	0.300 kg•m^2			0.300 kg•m^2
	Joint #5	0.300 kg•m^2			0.300 kg•m^2
	Joint #6	0.100 kg•m^2			0.100 kg•m^2
Standard I/O		In: 24/Out: 16			In: 24/Out: 16
Installation environments		Standard/ Cleanroom ISO Class 4/ Protected IP67	Standard		Standard
Available controllers		Built-in			Built-in
Safety standards		CE Mark: EMC Directive, Machinery Directive, RoHS Directive ANSI/RIA R15.06-2012 NFPA 79 (2007 Edition)			CE Mark: EMC Directive, Machinery Directive, RoHS Directive ANSI/RIA R15.06-2012 NFPA 79 (2007 Edition)
Power		110 and 220 VAC			48 VDC

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 2 kg payload (path coordinates optimized for maximum speed).
2 If the center of gravity is at the center of each arm. If the center of gravity is not at the center of each arm, set the eccentric quantity using the INERTIA command.

N-SERIES

6-AXIS ROBOTS



N-Series

The N-Series offers revolutionary technology that provides significant advantages for more efficient workspace utilization than typical 6-Axis robots. Packed with unique technology exclusive to Epson, N-Series robots set a new standard in 6-Axis technology with the world's first folding-arm design.

N2

World's first folding-arm design, ideal for assembly and parts handling

N6

Higher payloads and longer reach for load/unload applications

N-SERIES SPECIFICATIONS

		N2	N6
Arm length		450 mm	850/1,000 mm
Repeatability	**Joints #1, #2**	±0.02 mm	±0.030 mm/±0.040 mm
Payload	**Rated**	1 kg	3 kg
	Maximum	2.5 kg	6 kg
Installation environments		Standard	Standard/Cleanroom ISO Class 5 with ESD
Available controllers		RC700A	

N2

Scan Here for CAD Drawings

Space-saving, revolutionary design

- Arm length of 450 mm
- Payloads up to 2.5 kg
- World's first compact folding-arm design
- Reduces required workspace area vs. standard 6-Axis robots
- Maximizes motion efficiency for faster cycle times

SPECIFICATIONS

		N2-A450	
Mounting type		Tabletop	Ceiling
Degree of freedom		6	
Arm length	**P Point: through the center of J4/J5/J6**	450 mm	
Wrist flange surface		507 mm	
Weight (cables not included)		19 kg	
Repeatability	**Joints #1 – #6**	±0.020 mm	
Max. motion range	**Joint #1**	±180 deg	
	Joint #2	±180 deg	
	Joint #3	±180 deg	
	Joint #4	±195 deg	
	Joint #5	±130 deg	
	Joint #6	±360 deg	
Payload	**Rated**	1 kg	
	Maximum	2.5 kg	
Allowable moment of inertia[1]	**Joint #4**	0.200 kg•m²	
	Joint #5	0.200 kg•m²	
	Joint #6	0.080 kg•m²	
Electric lines		15 (15-Pin: D-Sub), 8 (8-Pin: RJ45) Cat5e	
Pneumatic lines		Φ6 mm × 2	
Installation environment		Standard	
Available controllers		RC700A	
Safety standards		CE Mark: EMC Directive, Machinery Directive, RoHS Directive ANSI/RIA R15.06-2012 NFPA 79 (2007 Edition)	

1 If the center of gravity is at the center of each arm. If the center of gravity is not at the center of each arm, set the eccentric quantity using the INERTIA command.

N6

Scan Here for CAD Drawings

Long reach, revolutionary design

- Arm lengths of 850 and 1,000 mm
- Payloads up to 6 kg
- World's first folding-arm design
- Ideal for confined spaces and load/unload applications

SPECIFICATIONS

		N6-A85x	N6-A10x
Mounting type		Ceiling	Tabletop/Ceiling
Degree of freedom		6	6
Arm length	**P Point: through the center of J4/J5/J6**	850 mm	1,000 mm
Wrist flange surface		960 mm	1,110 mm
Weight (cables not included)		64 kg	69 kg
Repeatability	**Joints #1 – #6**	±0.030 mm	±0.040 mm
Max. motion range	**Joint #1**	±180 deg	
	Joint #2	±180 deg	
	Joint #3	±180 deg	
	Joint #4	±200 deg	
	Joint #5	±125 deg	
	Joint #6	±360 deg	
Payload	**Rated**	3 kg	3 kg
	Maximum	6 kg	6 kg
Allowable moment of inertia[1]	**Joint #4**	0.420 kg•m²	
	Joint #5	0.420 kg•m²	
	Joint #6	0.140 kg•m²	
Electric lines		15 (15-Pin: D-Sub), 8 (8-Pin: RJ45) Cat5e	
Pneumatic lines		Φ6 mm × 2	
Installation environment		Standard	
Available controllers		RC700A	
Safety standards		CE Mark: EMC Directive, Machinery Directive, RoHS Directive ANSI/RIA R15.06-2012 NFPA 79 (2007 Edition)	

1 If the center of gravity is at the center of each arm. If the center of gravity is not at the center of each arm, set the eccentric quantity using the INERTIA command.

C-SERIES

6-AXIS ROBOTS

C-Series

With exceptional flexibility and a slim, compact design, C-Series robots provide an innovative solution for 6-Axis applications. Their small footprint makes them ideal for factories that need to save space. And their long arms enable them to access hard-to-reach areas in the workplace.

C4

Compact robots with high repeatability and fast cycle times

C8

Powerful robots with long reach and heavy payloads

C12

High-performance robots with heavy payload and second-generation GYROPLUS Technology

C-SERIES SPECIFICATIONS

		C4	C8	C12
Arm length		600/900 mm	700/900/1,400 mm	1,400 mm
Repeatability	**Joints #1 – #6**	±0.020/±0.030 mm	±0.020/±0.030/±0.050 mm	±0.050 mm
Payload	**Rated**	1 kg	3 kg	3 kg
	Maximum	4 kg (5 kg with arm-downward positioning)	8 kg	12 kg
Standard cycle time[1]		0.37/0.47 sec	0.31/0.35/0.53 sec	0.50 sec
Installation environments		Standard/Cleanroom ISO Class 3 with ESD	Standard/Cleanroom ISO Class 3 and 4 with ESD/Protected IP67	Standard/Cleanroom ISO Class 4 with ESD
Available controllers		RC700A		

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 1 kg payload (path coordinates optimized for maximum speed).

C4

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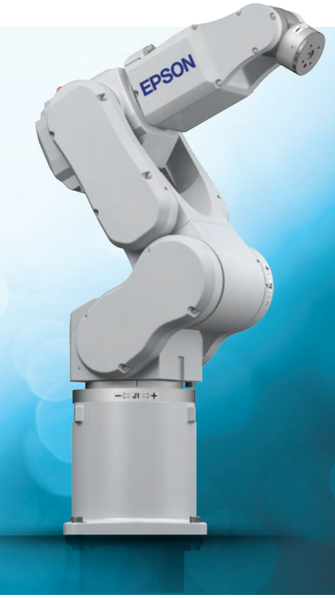


High speed and exceptional flexibility

- Arm lengths of 600 and 900 mm
- Payloads up to 4 kg
- Slim design and compact wrist—fits in tight spaces
- Cleanroom ISO Class 3 models available

SPECIFICATIONS

		C4-A601 (C4)		C4-A901 (C4L)	
Mounting type		Tabletop	Ceiling	Tabletop	Ceiling
Degree of freedom		6			
Arm length	**P Point: through the center of J4/J5/J6**	600 mm		900 mm	
Wrist flange surface		665 mm		965 mm	
Weight (cables not included)		27 kg		29 kg	
Repeatability	**Joints #1 – #6**	±0.020 mm		±0.030 mm	
Max. motion range	**Joint #1**	±170 deg			
	Joint #2	-160 ~ +65 deg			
	Joint #3	-51 ~ +225 deg			
	Joint #4	±200 deg			
	Joint #5	±135 deg			
	Joint #6	±360 deg			
Payload	**Rated**	1 kg			
	Maximum	4 kg			
Standard cycle time[1]		0.37 sec		0.47 sec	
Allowable moment of inertia[2]	**Joint #4**	0.150 kg•m²			
	Joint #5	0.150 kg•m²			
	Joint #6	0.100 kg•m²			
Electric lines		9-Pin (D-Sub)			
Pneumatic lines		Φ4 mm × 4			
Installation environments		Standard/Cleanroom ISO Class 3 with ESD			
Available controllers		RC700A			
Safety standards		CE Mark: EMC Directive, Machinery Directive, RoHS Directive UL1740 ANSI/RIA R15.06 NFPA 79			

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 1 kg payload (path coordinates optimized for maximum speed).
2 If the center of gravity is at the center of each arm. If the center of gravity is not at the center of each arm, set the eccentric quantity using the INERTIA command.

C8/C12

Scan Here for CAD Drawings

Long reach and heavy payload

- Arm lengths of 700, 900 and 1,400 mm
- Payloads up to 12 kg
- Slim design and compact wrist—fits in tight spaces
- Cleanroom ISO Class 3 (C8/C8L) and Class 4 (C8XL/C12XL) models available

SPECIFICATIONS

		C8-A701 (C8)	C8-A901 (C8L)	C8-A1401 (C8XL)	C12XL-A1401 (C12XL)
Mounting type		Tabletop/Ceiling/Wall			Tabletop
Degree of freedom		6			
Arm length	**P Point: through the center of J4/J5/J6**	711 mm	901 mm	1,400 mm	1,400 mm
Wrist flange surface		791 mm	981 mm	1,480 mm	1,480 mm
Weight (cables not included)		49 kg (Protected: 53 kg)	52 kg (Protected: 56 kg)	62 kg (Protected: 66 kg)	63 kg
Repeatability	**Joints #1 – #6**	±0.02 mm	±0.03 mm	±0.05 mm	±0.05 mm
Max. motion range	**Joint #1**	±240 deg			
	Joint #2	-158 ~ +65 deg		-135 ~ +55 deg	
	Joint #3	-61 ~ +202 deg			
	Joint #4	±200 deg			
	Joint #5	±135 deg			
	Joint #6	±360 deg			
Payload	**Rated**	3 kg			
	Maximum	8 kg			12 kg
Standard cycle time[1]		0.31 sec	0.35 sec	0.53 sec	0.50 sec
Allowable moment of inertia[2]	**Joint #4**	0.470 kg•m²			0.700 kg•m²
	Joint #5	0.470 kg•m²			0.700 kg•m²
	Joint #6	0.150 kg•m²			0.200 kg•m²
Electric lines		15-Pin (D-Sub), 8-Pin (RJ45), 6-Pin (for Force Sensor)			
Pneumatic lines		Φ6 mm x 2			
Installation environments		Standard/Cleanroom ISO Class 3 with ESD/Protected IP67			Standard/Cleanroom ISO Class 4 with ESD
Available controllers		RC700A			
Safety standards		CE Mark: EMC Directive, Machinery Directive, RoHS Directive UL1740 ANSI/RIA R15.06 NFPA 79			CE Mark: EMC Directive, Machinery Directive, RoHS Directive ANSI/RIA R15.06 NFPA 79

1 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 1 kg payload (path coordinates optimized for maximum speed).
2 If the center of gravity is at the center of each arm. If the center of gravity is not at the center of each arm, set the eccentric quantity using the INERTIA command.

Robot Controllers

Compact and intuitive, Epson controllers make automation configuration easy. Designed for use with both SCARA and 6-Axis robots, Epson's lineup provides advanced servo control for smooth motion and precise positioning. With integrated options available such as Vision Guidance, Force Guidance, Conveyor Tracking and more, Epson controllers provide true solution-based expandability.

All-in-One

Space-saving design with built-in controllers at an ultra low price

RC90B

Great performance at an affordable price

RC700A

Powerful feature set with ultra fast processing

RC700D

High-performance controller for our most advanced SCARA robots

Advanced controllers to meet your automation needs

- **Powerful performance, compact design**
  —built for space-constrained environments; able to support everything from simple to high-end robots
- **Supports both SCARA and 6-Axis robots**
  —simplifies the lineup with common platforms
- **Full lineup of both SCARA and 6-Axis controllers**
  —choose the one best suited for your application
- **Easy to configure/setup**
  —front access (RC90B, RC700A and RC700D); intuitive panel; consolidated controls, all on one side, for easy changeouts
- **Advanced servo control system**
  —enables the robot to quickly perform smooth, precise motions
- **Slots for optional components**
  —supports a wide variety of fully integrated options

All-in-One

Space-saving design, ultra low cost

- Supports TB-Series SCARA and VT-Series 6-Axis robots
- Comes standard with 110 V and 220 V power
- Use as standalone, PLC slave or with a PC
- Wide variety of integrated options including Vision Guide, IntelliFlex™ Feeding System, .Net connectivity, EtherNet/IP®, DeviceNet®, PROFIBUS and more

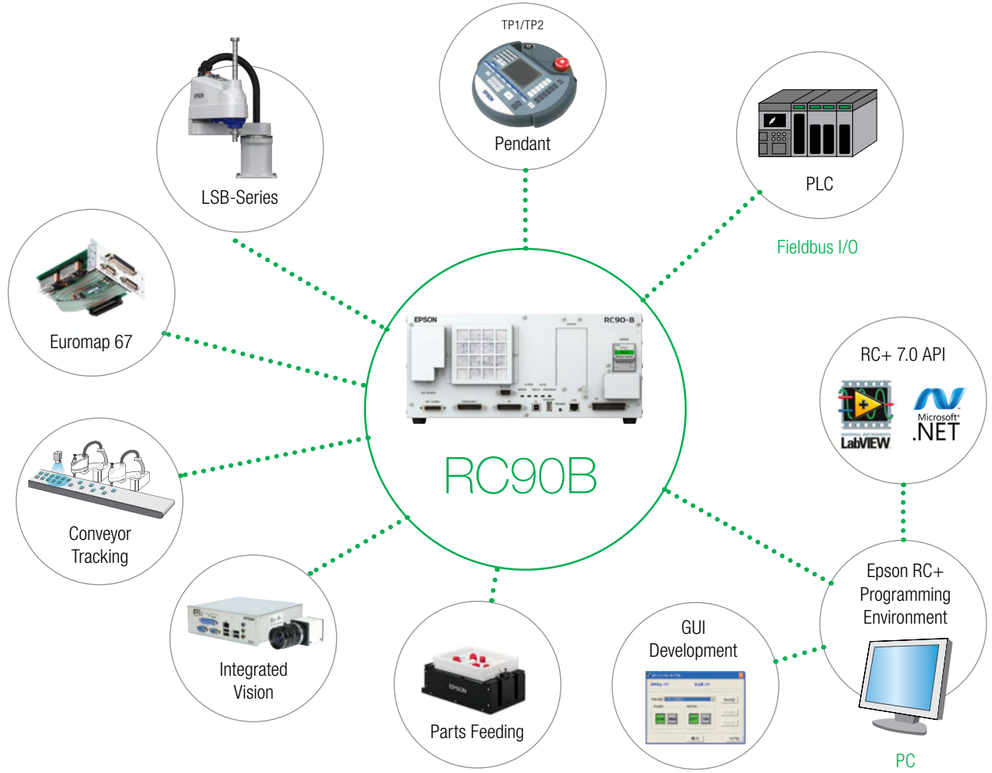
SYSTEM CAPABILITIES

RC90B

Great performance at an affordable price

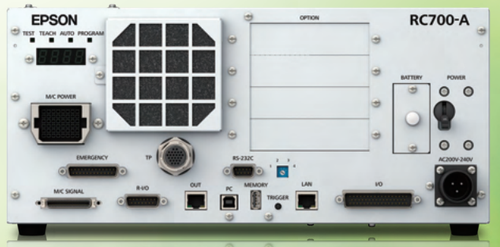
- Supports LSB-Series SCARA robots
- Use as standalone, PLC slave or with a PC
- Wide variety of integrated options including Vision Guide, Force Guide, IntelliFlex Feeding System, .Net connectivity, EtherNet/IP, DeviceNet, PROFIBUS, Expansion I/O, Conveyor Tracking and more

SYSTEM CAPABILITIES



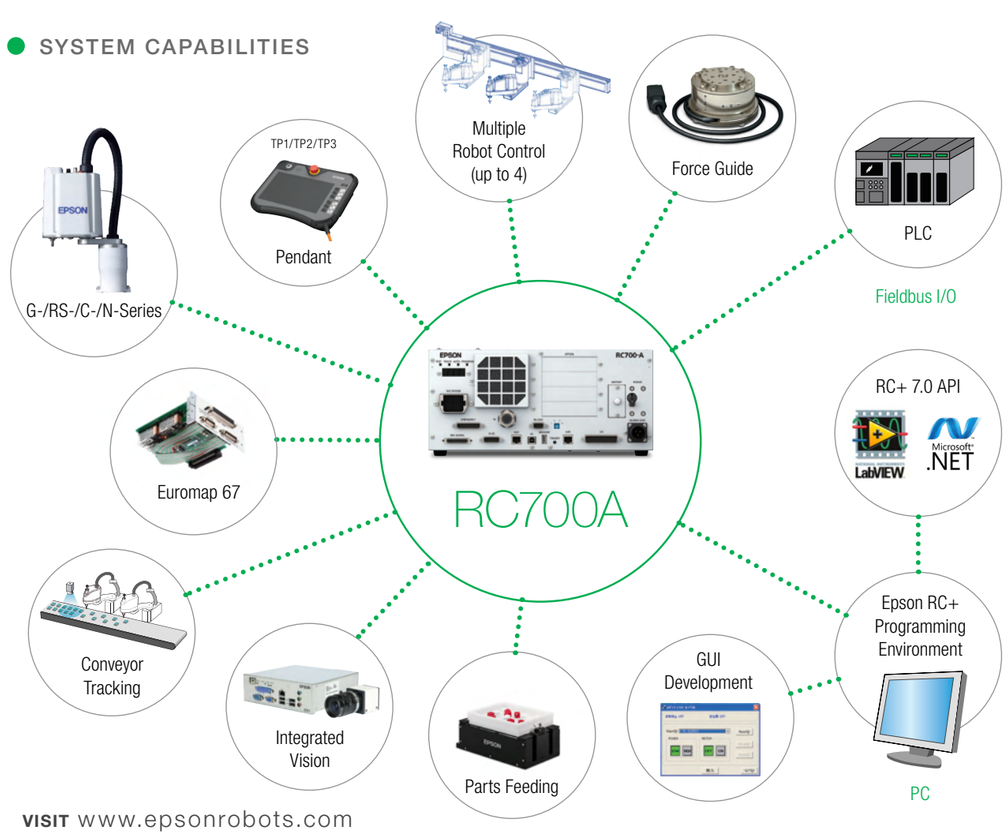
RC700A

Powerful performance with ultra fast processing



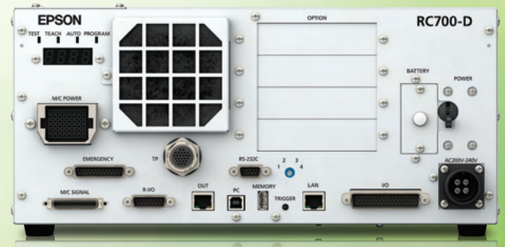
- Supports G- and RS-Series SCARA and C- and N-Series 6-Axis robots
- Use as standalone, PLC slave or with a PC, as well as Modules
- Wide variety of integrated options including Vision Guide, Force Guide, IntelliFlex Feeding System, .Net connectivity, EtherNet/IP, DeviceNet, PROFIBUS, Expansion I/O, Conveyor Tracking and more

SYSTEM CAPABILITIES



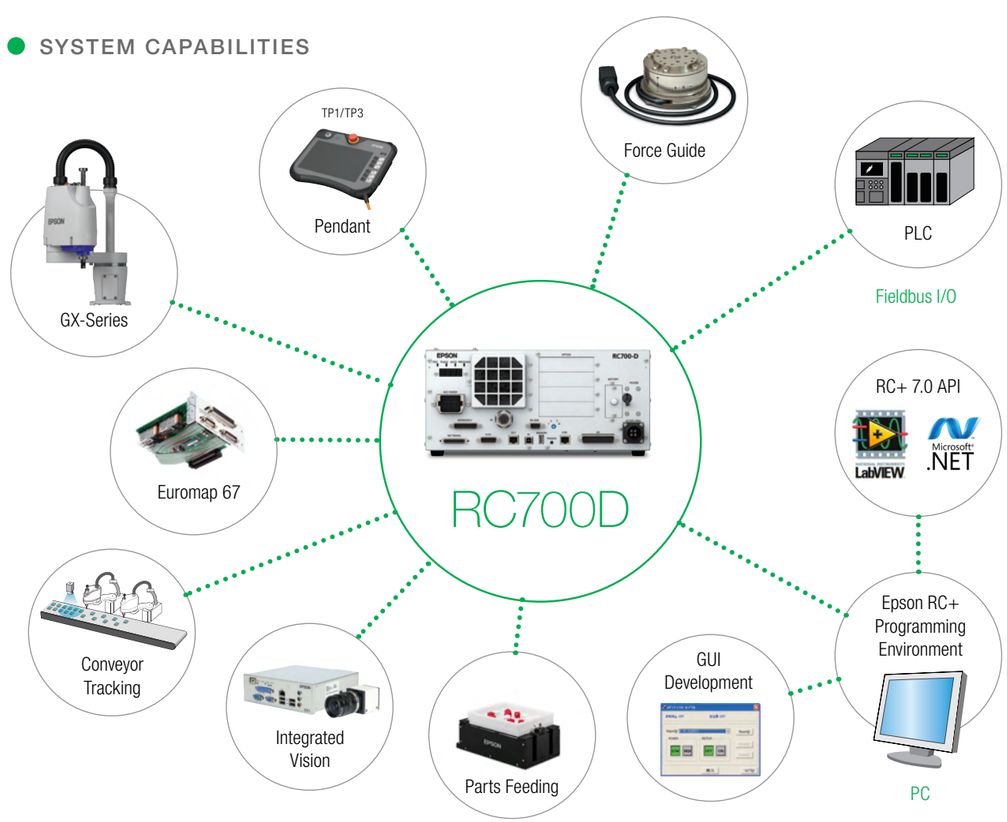
RC700D

High-performance controller for our most advanced SCARA robots



- Supports GX-Series SCARA robots
- Use as standalone, PLC slave or with a PC, as well as Modules
- Wide variety of integrated options, including Vision Guide, Force Guide, IntelliFlex Feeding System, .Net connectivity, EtherNet/IP, DeviceNet, PROFIBUS, Expansion I/O, Conveyor Tracking and more

SYSTEM CAPABILITIES



SPECIFICATIONS

Model		All-in-One		RC90B	
Robot manipulator control	Programming language and robot control software	Epson RC+ 7.x Epson RC+ Express 1.x		Epson RC+ 7.x Epson RC+ Express 1.x	
	Joint control	Up to six (6) joints simultaneous control, Software AC servo control		Up to four (4) joints simultaneous control, Software AC servo control	
	Speed control	PTP motion: Programmable in the range of 1% to 100% CP motion: Programmable (actual value to be manually entered)		PTP motion: Programmable in the range of 1% to 100% CP motion: Programmable (actual value to be manually entered)	
	Acceleration/ deceleration control	PTP motion: Programmable in the range of 1% to 100% Automatic CP motion: Programmable (actual value to be manually entered)		PTP motion: Programmable in the range of 1% to 100% Automatic CP motion: Programmable (actual value to be manually entered)	
	Number of manipulators	1		1	
Positioning control		PTP (Point-To-Point)/CP (Continuous Path)		PTP (Point-To-Point)/CP (Continuous Path)	
Memory capacity		Maximum object size: 8MB Point data area: 1,000 points (per file) Backup variable area: Max. 400KB (includes the memory area for the management table) Approx. 4,000 variables (depends on the size of array variables)		Maximum object size: 8MB Point data area: 1,000 points (per file) Backup variable area: Max. 400KB (includes the memory area for the management table) Approx. 4,000 variables (depends on the size of array variables)	
External input/ output signals (standard)	Standard Input Output	VT-Series: Input: 24/Output: 16 TB-Series: In: 18/Out: 12/ Hand: In: 6/Out: 4	Including 8 inputs, 8 outputs with remote function assigned; assignment change allowed	Input: 24 Output: 16	Including 8 inputs, 8 outputs with remote function assigned; assignment change allowed
	Standard I/O drive unit	—		—	
Communication interface (standard)	Ethernet	1 channel		1 channel	
	USB	1 port		1 port	
Option boards (special slot)	I/O	—		Input: 24 per board Output: 16 per board	Maximum of 2 boards allowed
	Analog I/O	—		1 channel	
	Euromap 67	—		Input: 15 per board/Output: 16 per board	
	RS-232C	—		2 channels/board	Maximum of 2 boards allowed
	Fieldbus I/O slave	PROFINET PROFIBUS-DP DeviceNet CC-Link Ethernet/IP EtherCAT®	Maximum of 1 board allowed	1 channel/board PROFINET PROFIBUS-DP DeviceNet CC-Link Ethernet/IP EtherCAT	Maximum of 1 board allowed
	Pulse generator	—		4 axes/board	Maximum of 2 boards allowed
Option boards (PCI or PCIe slots)	Fieldbus I/O master	PROFIBUS-DP DeviceNet Ethernet/IP	—	1 channel/board PROFIBUS-DP DeviceNet Ethernet/IP	Maximum of 1 board allowed
Security		Password-based protection levels can be set to restrict access to some parts of the Epson RC+ system, helping prevent accidental or unauthorized alteration of control programs when multiple operators need to have access to basic controls. Keeps a log of changes made to source code.			
Safety features		Emergency stop switch / Safety door input / Low power mode / Dynamic brake / Encoder cable disconnection error detection / Motor overload detection / Irregular motor torque (out-of-control Manipulator) detection / Motor speed error detection / Positioning overflow - servo error - detection / Speed overflow - servo error - detection / CPU irregularity detection / Memory check-sum error detection / Overheat detection at the Motor Driver Module / Relay welding detection / Over-voltage detection / AC power supply voltage reduction detection / Temperature error detection / Fan error detection		Emergency stop switch / Safety door input / Low power mode / Dynamic brake / Encoder cable disconnection error detection / Motor overload detection / Irregular motor torque (out-of-control Manipulator) detection / Motor speed error detection / Positioning overflow - servo error - detection / Speed overflow - servo error - detection / CPU irregularity detection / Memory check-sum error detection / Overheat detection at the Motor Driver Module / Relay welding detection / Over-voltage detection / AC power supply voltage reduction detection / Temperature error detection / Fan error detection	
Power source		AC 110 V to AC 220 V/Single phase 50/60 Hz		AC 200 V to AC 240 V/Single phase 50/60 Hz	
Weight		Varies per robot model		7.5 kg	

RC700A		RC700D	
Epson RC+ 7.x Epson RC+ Express 1.x (not supported with N- and RS-Series)		Epson RC+ 7.x Epson RC+ Express 1.x	
Up to six (6) joints simultaneous control, Software AC servo control		Up to six (6) joints simultaneous control, Software AC servo control	
PTP motion: Programmable in the range of 1% to 100% CP motion: Programmable (actual value to be manually entered)		PTP motion: Programmable in the range of 1% to 100% CP motion: Programmable (actual value to be manually entered)	
PTP motion: Programmable in the range of 1% to 100%; Automatic CP motion: Programmable (actual value to be manually entered)		PTP motion: Programmable in the range of 1% to 100%; Automatic CP motion: Programmable (actual value to be manually entered)	
4		1	
PTP (Point-To-Point)/CP (Continuous Path)		PTP (Point-To-Point)/CP (Continuous Path)	
Maximum object size: 8MB Point data area: 1,000 points (per file) Backup variable area: Max. 400KB (includes the memory area for the management table) Approx. 4,000 variables (depends on the size of array variables)		Maximum object size: 8MB Point data area: 1,000 points (per file) Backup variable area: Max. 400KB (includes the memory area for the management table) Approx. 4,000 variables (depends on the size of array variables)	
Input: 24 Output: 16	Including 8 inputs, 8 outputs with remote function assigned; assignment change allowed	Input: 24 Output: 16	Including 8 inputs, 8 outputs with remote function assigned; assignment change allowed
Input: 24 Output: 16	Per drive unit	—	
1 channel		1 channel	
1 port		1 port	
Input: 24 per board Output: 16 per board	Maximum of 4 boards allowed	Input: 24 per board Output: 16 per board	Maximum of 4 boards allowed
1 channel		1 channel	
Input: 15 per board/Output: 16 per board		Input: 15 per board/Output: 16 per board	
2 channels/board	Maximum of 2 boards allowed	2 channels/board	Maximum of 2 boards allowed
1 channel/board PROFINET PROFIBUS-DP DeviceNet CC-Link Ethernet/IP EtherCAT	Maximum of 1 board allowed	1 channel/board PROFINET PROFIBUS-DP DeviceNet CC-Link Ethernet/IP EtherCAT	Maximum of 1 board allowed
4 axes/board	Maximum of 4 boards allowed	4 axes/board	Maximum of 4 boards allowed
1 channel/board PROFIBUS-DP DeviceNet Ethernet/IP	Maximum of 1 board allowed	1 channel/board PROFIBUS-DP DeviceNet Ethernet/IP	Maximum of 1 board allowed
Password-based protection levels can be set to restrict access to some parts of the Epson RC+ system, helping prevent accidental or unauthorized alteration of control programs when multiple operators need to have access to basic controls. Keeps a log of changes made to source code.			
Emergency stop switch / Safety door input / Low power mode / Dynamic brake / Encoder cable disconnection error detection / Motor overload detection / Irregular motor torque (out-of-control Manipulator) detection / Motor speed error detection / Positioning overflow - servo error - detection / Speed overflow - servo error - detection / CPU irregularity detection / Memory check-sum error detection / Overheat detection at the Motor Driver Module / Relay welding detection / Over-voltage detection / AC power supply voltage reduction detection / Temperature error detection / Fan error detection		Emergency stop switch / Safety door input / Low power mode / Dynamic brake / Encoder cable disconnection error detection / Motor overload detection / Irregular motor torque (out-of-control Manipulator) detection / Motor speed error detection / Positioning overflow - servo error - detection / Speed overflow - servo error - detection / CPU irregularity detection / Memory check-sum error detection / Overheat detection at the Motor Driver Module / Relay welding detection / Over-voltage detection / AC power supply voltage reduction detection / Temperature error detection / Fan error detection	
AC 200 V to AC 240 V/Single phase 50/60 Hz		AC 200 V to AC 240 V/Single phase 50/60 Hz	
11 kg		11 kg	

Development Software: Epson RC+ and Epson RC+ Express

Epson RC+ and Epson RC+ Express offer the ultimate selection of powerful, easy-to-use features, reducing the time needed to develop automated robot solutions. Epson RC+ advanced software includes fully integrated options such as Vision Guidance, Force Guidance, Conveyor Tracking, Parts Feeding and more. Epson RC+ Express features an easy-to-learn, block-style robot teaching environment, ideal for new users with little or no coding experience.

Epson RC+

Comprehensive suite of advanced tools and features in one convenient, integrated environment

Epson RC+ Express

Intuitive, no-code, visual-based robot teaching environment

The perfect choice for automation experts and new users alike, Epson makes it easy to create an array of industrial robot solutions with two powerful development environments.

- Software options for simple or complex applications
- Easy-to-learn programming (Epson RC+) or no-code programming environment (Epson RC+ Express)
- Intuitive and easy to learn
- 3D simulator
- Quick deployment of your robotic system

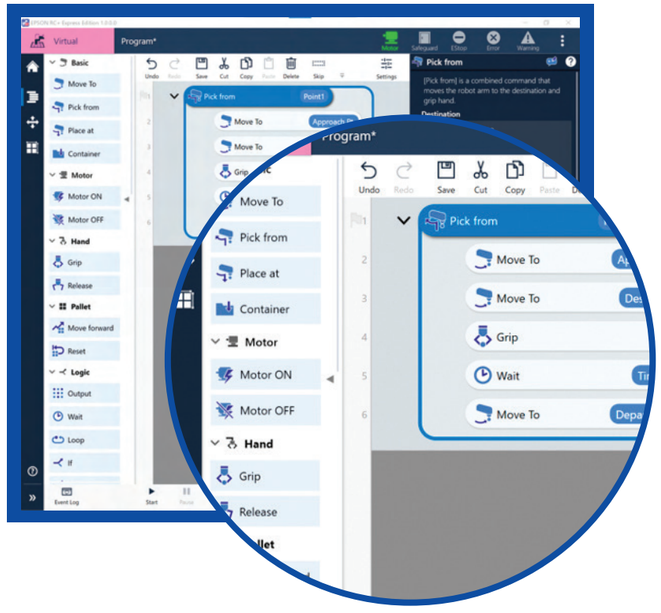
Epson RC+ Express

Get your robot system up and running fast

Epson RC+ Express is a simple, visual-based teaching environment built for users who are new to robot automation and have little to no programming experience.

NO-CODE, EASY-TO-USE ROBOT TEACHING ENVIRONMENT

Get the power and flexibility of a scripted-text language with an easy-to-use robot programming environment. Epson RC+ Express is designed for use with Epson SCARA and 6-Axis robots, from the All-in-One TB-Series and VT6L to the highest-performance G-, GX- and C-Series.



SIMPLE TO NAVIGATE

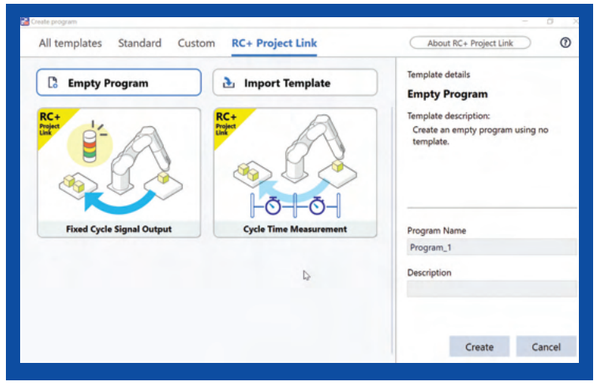
Clear, intuitive, visual user interface makes it easy to learn and manage key functions, such as jogging, gripper control and motion. Take advantage of easy jog when manipulating 6-Axis robots, move effortlessly between linear and joint motion, and easily align the robot tool face to different planes with a single click.

Robot recovery has never been easier—by using the rollback feature after an event, the robot can be returned to a previous known position, allowing an easy restart to the system.

EXTENDED CAPABILITIES

Experienced Epson RC+ users can take advantage of the extended SPEL+ commands to simplify programs and complete more advanced tasks, while retaining the simple yet powerful Epson RC+ Express interface.

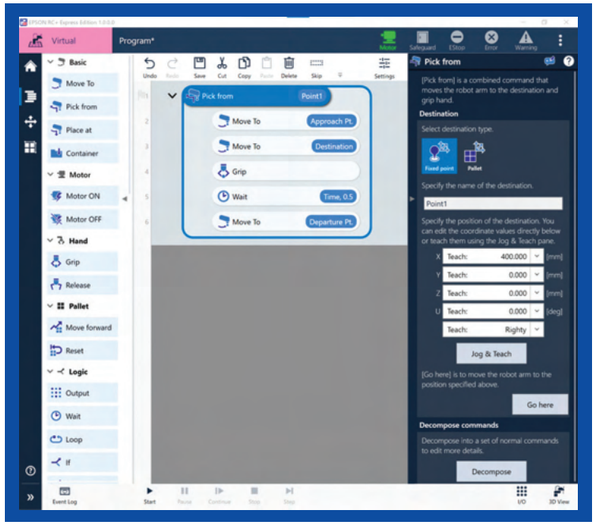
The optional Epson RC+ Project Link allows users to create advanced functions—such as Vision Guide or Force Guide—in Epson RC+ and then bring them into Epson RC+ Express programs. Additionally, Epson RC+ Express commands can be translated to the SPEL+ language, allowing easy transition from Epson RC+ Express to Epson RC+.



QUICK SETUP

Epson's proprietary Focus Assist technology provides quick-teach tools with auto-generated fields for fast application setup. Visual indicators highlight missing inputs to complete the function, such as quickly teaching a point. Wizards take users step-by-step to easily teach tools and pallets.

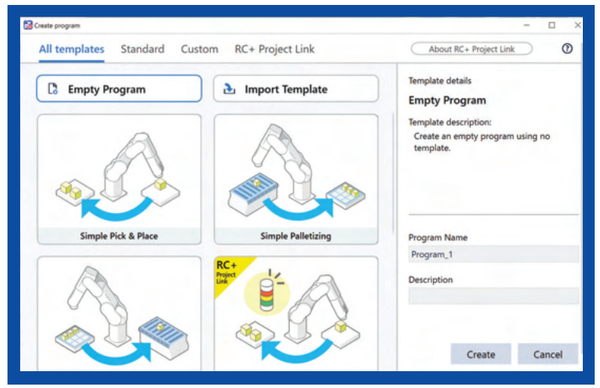
Once running, programs can be protected to reduce the risk of accidental program changes, all while allowing points to be re-taught to account for normal production variability.



COMMON APPLICATION TEMPLATES

Quickly create common applications, such as pick-and-place or palletizing and depalletizing, with premade, ready-to-use template programs. Learn on your own using the online tutorials with step-by-step instructions for Epson RC+ Express.

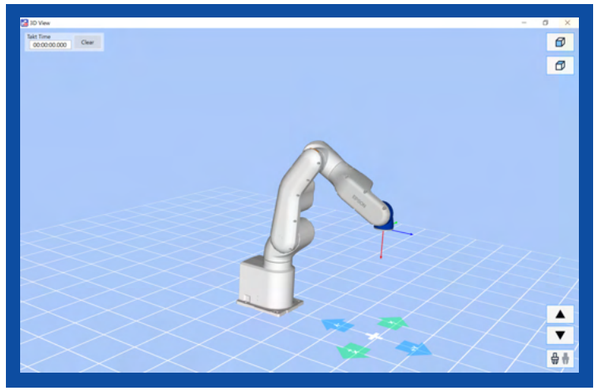
Templates are even provided for the optional Project Link, which allows the use of more advanced options, such as Vision Guide, Force Guide and Parts Feeding.



3D SIMULATOR

Conveniently program and fine-tune applications with the built-in 3D simulator before your hardware has even arrived. Teach points, create motion commands and even simulate inputs and outputs to develop your application offline.

Rehearsal Mode allows the robot to be operated at low power and speed, and if an unexpected motion or action occurs, the robot can be stopped by lifting your finger from the touchpad, reducing risk of damage to the robot and the workcell.



TABLET-BASED WINDOWS OS ENVIRONMENT

Compatible with touchscreen devices to easily create robot applications. Drag and drop functions and easily change their order by sliding them around. Cut and paste commands and points to speed application development. Use sliders to easily configure the robot speed to meet your throughput requirements.

Epson RC+

The ultimate choice for robot system development

Epson RC+ offers a powerful set of tools and features that redefine automation efficiency. A comprehensive solution for virtually any application, Epson RC+ provides seamless integration, with all components working together in one integrated environment.

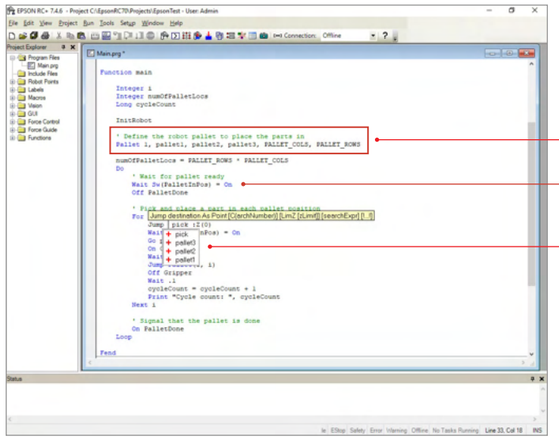
All-inclusive development environment

- Projects
- Robot manager
- Task manager
- Run window
- Operator window
- Jog and teach window
- I/O monitor
- Offline development
- Wizards
- Project explorer
- Toolbar customization
- 3D simulator

EDITOR

Auto-assist makes editing easier than ever

Epson RC+ includes powerful editing capabilities to minimize mistakes and streamline program development. In addition to basics such as cut, copy and paste, it also includes Syntax Assist, auto-indent, color-based command usage, comment blocks, indent/outdent, find/replace and more.



Color-based editor where keywords are blue, parameters are black, comments are green and incorrect syntax is red.

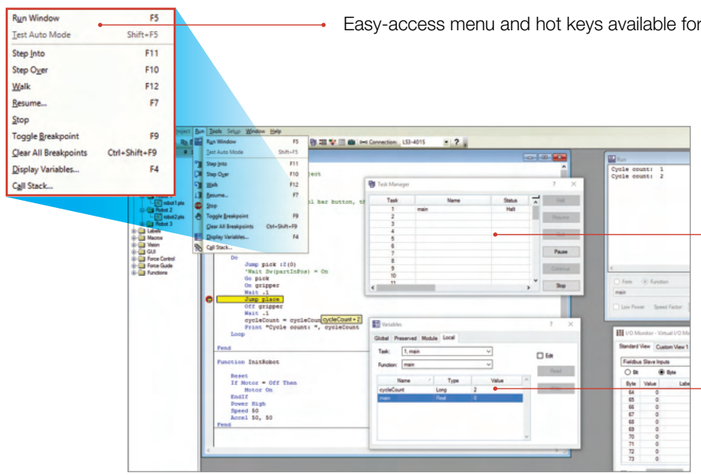
Automatic indenting of code contained in a function block for easy readability.

Syntax Assist helps users type or select the proper syntax for commands and their associated parameters.

INTEGRATED DEBUGGER

Easily identify issues in record time

The integrated debugger offers many clever ways to check the status of your program or identify issues you may find while running it. The Epson debugger allows you to check specified variables, view the value of those variables in real time, set break points, perform a single-step execution or jump over certain steps. You can also step into a function to view more details.



Easy-access menu and hot keys available for commonly used debugging tools.

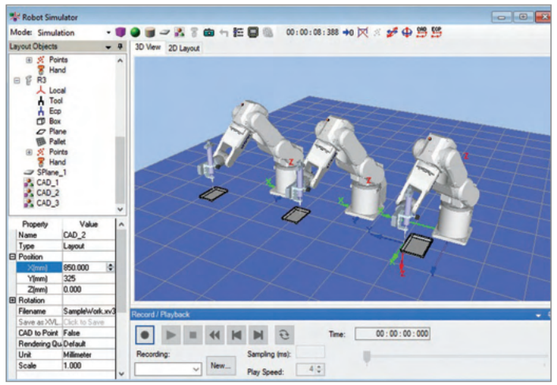
Task manager provides quick access to view status, start, stop, pause and continue Epson RC+ tasks.

Real-time display of local and/or global variables.

3D SIMULATOR

Build and fine-tune your application before hardware setup

Take automation development to the next level with a virtual test run. Epson's workcell simulator means you can program your workcell, even before your hardware has arrived. See a 3D simulation of your application in action—in real time. You can even add additional components that may be a part of the workcell, such as a table, feeder or various types of guarding. Add a tool to the robot's arm and implement your program to examine the efficiency of the application.



Need to examine how multiple robots might affect productivity? Give it a test run with a detailed, simulated workcell.

Full-featured simulator supports up to three robots and peripherals such as guarding, tools, parts and more.

Cycle-time calculation

- Calculate cycle time based on real application execution

Offline application checking

- Program can be created and debugged from standalone PCs
- Debugged programs can be rolled out directly to plant floor workcells

Machine vision simulation

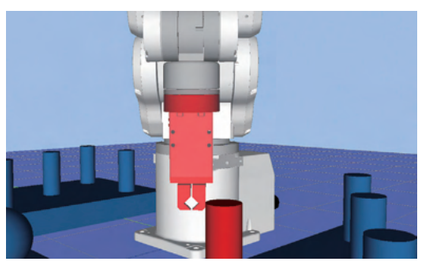
- Machine vision image processing input can also be used within simulations

Record and playback functions

- Recording and playback functions make it easy to include still images and movies in presentations

Clearance checking

- Choosing the right robot is easy because you can check all necessary workcell and peripheral equipment



Vision Guide simulation supported with Epson RC+ 7.0

SPEL+ ROBOT LANGUAGE

Epson's SPEL+ is a powerful yet easy-to-learn-and-use programming language for robot automation applications. With 500+ commands and statements, including motion functions, I/O control, variables and data types, program control and more, SPEL+ can be used for both complex and simple applications.

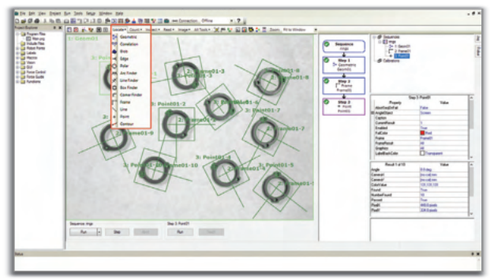
Example Program

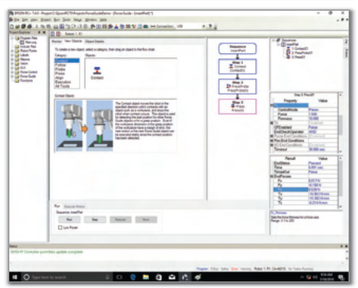
```
Function main
    Motor   On              *turn motor power on
    Power   High            *Power mode set high
    Speed   100             *Speed 100%
    Accel   100, 100        *Acceleration/Deceleration 100%

    If Sw(partok) = On Then *Checking if good part
        Jump  goodparts     *move arm to goodpart pile
    Else
        Jump  badparts      *move arm to bad part pile
    EndIf

Fend
```

INTEGRATED ENVIRONMENT

One source, one comprehensive solution

Epson software offers easy integration of Epson robots with various automation options, including Vision Guide, Force Guide, IntelliFlex Parts Feeding, Conveyor Tracking and more. Built as a comprehensive solution for any given application, it provides seamless integration, allowing all components to interface with one another in a single environment.





Vision Guide and Force Guide are just two of the many integrated options available with Epson RC+.

Integrated Solutions

Enhance your robot automation solution with integrated options such as Vision Guide, Force Guide, IntelliFlex Parts Feeding and more. These powerful solutions make it easy to quickly build various applications without having to worry about peripheral communication setups and development from multiple environments. Instead, you can focus on maximizing the efficiency of your application.

Vision Guide

Integrated vision guidance with easy configuration and collaboration

IntelliFlex

High-performance parts-feeding solution with easy integration

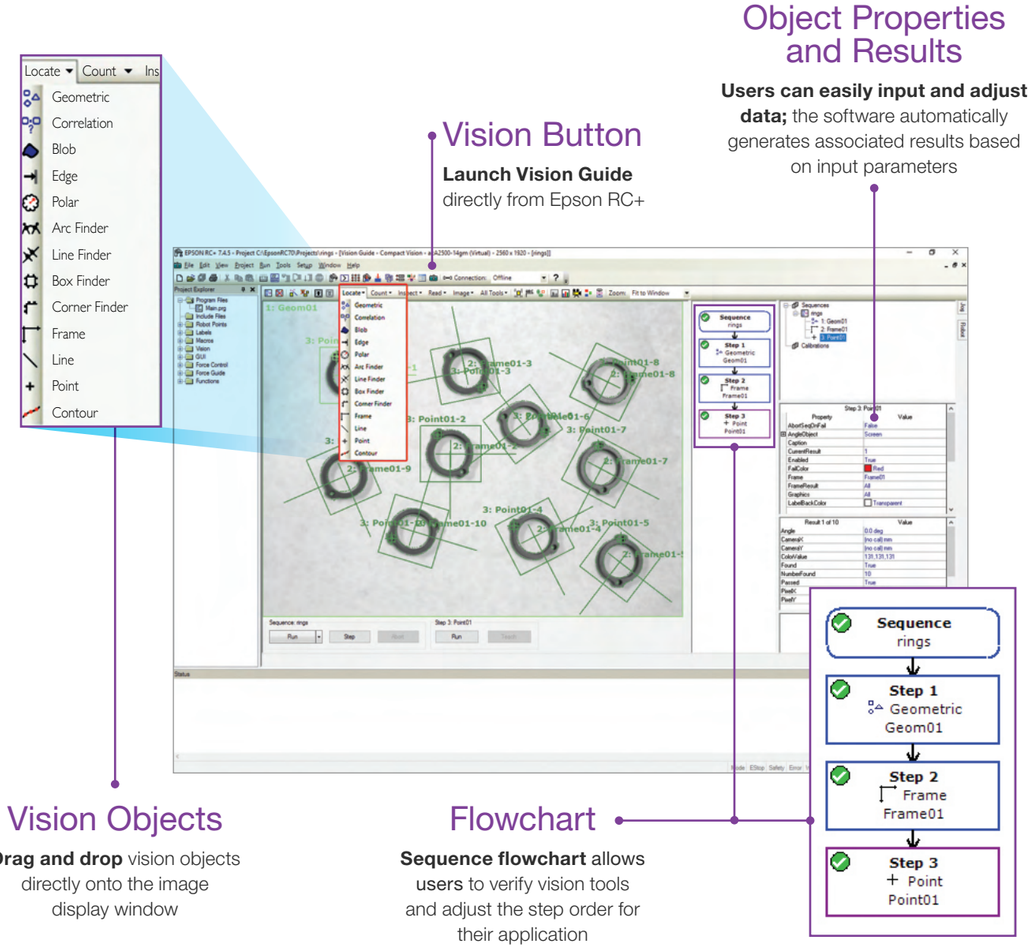
Force Guide

Intuitive robot force guidance for high-precision performance

VISION GUIDE

Vision guidance made easy

Epson Vision Guide makes precision robotic guidance easy to use. Fully integrated within the Epson RC+ development environment for easy configuration and calibration, this intuitive solution features a point-and-click interface that makes it simple for users of all levels. It also features wizards and auto calibration methods, plus a combination robot/vision simulator for rapid offline testing. With a common software environment for both robots and vision guidance, Epson Vision Guide allows for fast development and simplified maintenance. An efficient and versatile solution, it also includes tools for inspection, gauging, barcode reading and much more.



Object Properties and Results

Users can easily input and adjust data; the software automatically generates associated results based on input parameters

Vision Button

Launch Vision Guide directly from Epson RC+

Vision Objects

Drag and drop vision objects directly onto the image display window

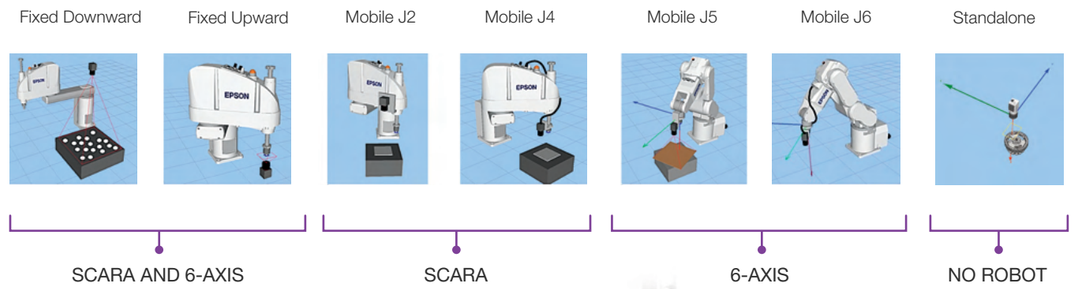
Flowchart

Sequence flowchart allows users to verify vision tools and adjust the step order for their application

VISION GUIDE

True robot geometry-based calibration

Unlike common mapping-based calibration, Epson Vision Guide uses a powerful geometric-based calibration solution to improve the precision of camera-to-robot-coordinate system translation. Reduce calibration time and improve consistency with the integrated calibration wizard and easy step-by-step instructions. Multiple calibrations for both 6-Axis and SCARA robots, including fixed-downward, fixed-upward and those with mobile-joint-mounted cameras, are supported.



Versatile tool set

Geometric
Finds a model based on geometric features. Used for determining position and orientation.

Blob
Computes geometric, topological and other image features. Used for determining presence/absence, size, positioning and orientation.

Correlation
Measures quality compared to previously trained features for alignment, inspection, position and orientation.

Edge
Locates edges by identifying changes in grey value from dark to light or light to dark.

ImageOp
Performs morphology, convolution, flip, binarize, rotate and more for a region of interest.

Polar
Uses correlation of a rotational area to determine object orientation.

OCR
Optical Character Recognition is used to recognize character strings in an image.

CodeReader
Reads bar or two-dimensional codes, including data matrix and others.

ColorMatch
Detects user-defined colors.

LineFinder
Determines the location of a line in an image.

LineInspector
Identifies deviations on a linear path between two points.

ArcFinder
Determines the radius and center point of an arc or major/minor axes and the angle of an ellipse.

ArcInspector
Determines abnormalities in the arc of a circle/ellipse.

DefectFinder
Compares a template image to an input image to identify defects.

Frame
Provides dynamic position reference for other vision objects.

Line
Defines a line between two objects.

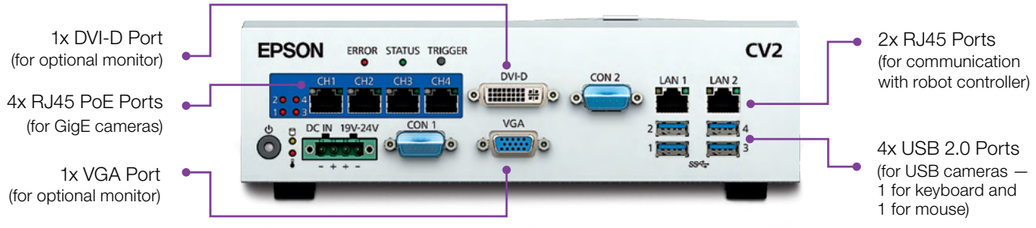
Point
Defines reference positions for other objects.

BoxFinder
Determines the center of an object.

CornerFinder
Identifies the intersection position of two lines that form a corner.

Contour
Generates a contour based on the external shape of an object.

Full-featured, integrated solution



SPECIFICATIONS

System		CV2SA	CV2HA	PV1
Robot controller		RC700A, RC90, RC90B, TB-Series, VT-Series		
Cameras supported (Epson cameras only)		GigE: Mono (0.3 MP, 1.3 MP, 2 MP, 5 MP, 10 MP and 20 MP) and Color (2 MP, 5 MP, 10 MP and 20 MP) USB: Mono (0.3 MP, 1.3 MP and 5 MP) and Color (1.3 MP, 5 MP)		
Vision tools		Locate: Geometric, Correlation, Blob, Edge, Polar, ArcFinder, LineFinder, BoxFinder, CornerFinder, Frame, Line, Point and Contour Count: Blob, Correlation, Geometric Inspect: Blob, DefectFinder, Line, LineInspector, ArcInspector and ColorMatch Read: CodeReader and OCR Image: ImageOp and Text		
Quantity of connectable cameras		Up to 6 cameras (2 USB and 4 GigE cameras)		Up to 8 GigE cameras
Image processing speed		Standard type	High-speed type	N/A
Safety standards		CE, UL, KC		N/A
Dimensions W x D x H (excluding rubber feet)		232 mm x 175 mm x 70 mm		N/A
Operating temperature and humidity		5 – 40 deg C, 20% – 80% (non-condensing)		N/A
Direction of installation		Horizontal or Vertical		N/A
Power source voltage		DC 19 V – 24 V		N/A
Rated electric current		11.57 A (at 19 V DC) – 9.16 A (at 24 V DC)		N/A
Weight		2.1 kg		N/A
Interface (connection)	Ethernet (for communication with Robot Controller)	RJ45: 4 ports (1000 Mbps); Power over Ethernet (PoE) supported; can connect to HUB or Switch		N/A
	Ethernet (for GigE camera)	RJ45: 4 ports (1000 Mbps); Power over Ethernet (PoE) supported		
	USB	USB 2.0: 4 ports (for USB Camera, USB Memory, Mouse, Keyboard)		
	Monitor connection	VGA: 1 port, DVI-D: 1 port (SXGA fixed) The 2 ports display the same output (mirror display)		
	CON1, CON2	Not available		
CV2 standard accessories		Mounting plates (1 set), power supply connector (1 pc), connector cap for CON (2 pcs)		N/A

The smarter parts singulation solution

Powered by Epson robots, IntelliFlex Software and Vision Guide, the IntelliFlex Feeding System delivers a simplistic feeding solution to accommodate a wide variety of parts. Integrated with Epson RC+ Development Software, the IntelliFlex Feeding System offers easy setup and configuration. Its point-and-click interface helps reduce the typical development time required for advanced applications. With four feeder sizes available (IntelliFlex 80, 240, 380 and 530), the system can accommodate part sizes ranging from 3 mm to 150 mm. The IntelliFlex system also offers intelligent auto-tuning for fast setup and flexible parts changeover. And multi-axis vibration technology provides optimized parts control and singulation.

IntelliFlex 240—Ideal for parts ranging from 5 mm – 40 mm

IntelliFlex 80—Ideal for parts ranging from 3 mm – 15 mm

Point-and-click setup and configuration

Fully integrated with the Epson RC+ Development Software, the IntelliFlex Feeding System makes setup and configuration easier than ever. Featuring a point-and-click interface, it can help reduce development time for advanced applications, often taking it from weeks down to days.

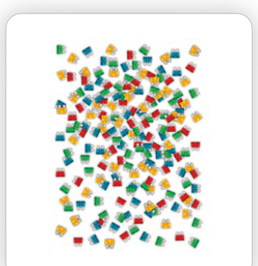
EPSON SYSTEM SETUP

1. **Vision Programming**
   - Built-in robot-to-vision calibration and point-and-click programming
2. **Parts Tuning**
   - Automatic parts tuning with vision feeder integration
3. **Parts Control Adjustment**
   - Configuration wizard for defining part separation pickup area and more

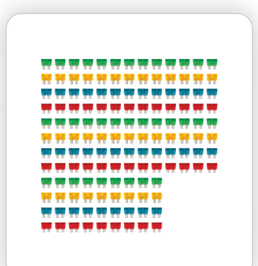
TYPICAL SYSTEM SETUP

1. **Feeder Communications**
   - Low-level protocol using feeder command set
2. **Feeder Tuning**
   - Getting parts to move properly
3. **Vision Setup and Calibration**
   - Calibrating vision system to robot
4. **Vision Programming**
   - Finding parts reliably
5. **System Programming**
   - Robot + Feeder + Vision coordination
6. **Optimization**
   - Fine-tuning and performance optimization

Turn this…



Into this…



With this.

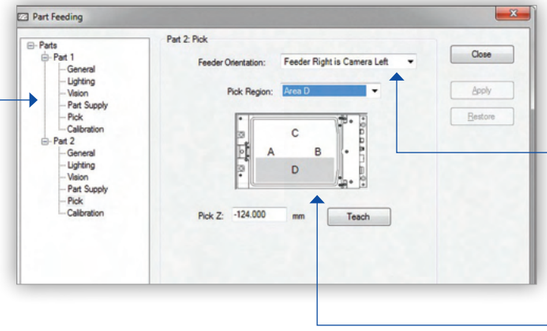
With multi-axis vibration technology, designed to optimize parts control.

Precision parts calibration with smart auto-tuning

Epson RC+ Development Software also features an intuitive wizard to guide users through customized calibration. Step by step, this wizard automatically determines the exact values needed for optimum tuning and calibration.

Part pickup regions maximize parts throughput

Easily set parameters specific to each part, no coding required

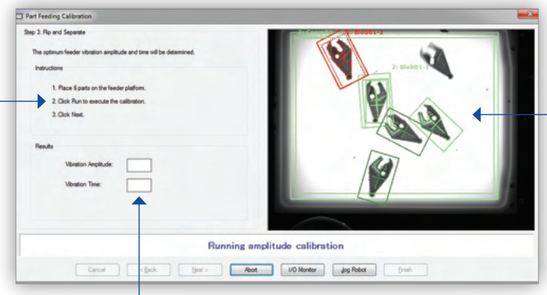


Configures feeder orientation to properly select the pickup area without needing to modify the physical application layout

Defines parts pickup area to optimize cycle time

Parts calibration (tuning) wizard reduces tuning time

3 simple steps to set up calibration parameters



Integrated image display window to show part separation results

Automatically computes and displays the tuning parameters, vibration amplitude and vibration time

IntelliFlex Feeding System

FLEXIBLE FEEDER SPECIFICATIONS

Model Name	IntelliFlex 80	IntelliFlex 240	IntelliFlex 380	IntelliFlex 530
Model number	RIF80	RIF240	RIF380	RIF530
Part size dimensions	3 mm – 15 mm	5 mm – 40 mm	15 mm – 60 mm	30 mm – 150 mm
Max. surface load per feeder	0.05 kg	0.40 kg	1.5 kg	2.0 kg
Communication	Ethernet (TCP/IP)			
Power supply	24 V/6 A	24 V/8 A	24 V/20 A	24 V/20 A
Vibration platform (length x width)	65 mm x 52 mm	195 mm x 150 mm	254 mm x 325 mm	427 mm x 371 mm
Footprint (length x width x height)	320 mm x 65 mm x 140 mm	300 mm x 171 mm x 132 mm	499 mm x 257 mm x 307 mm	600 mm x 372 mm x 320 mm
Compatible robot series	SCARA: G-/LSB-/RS-, TB-, GX-Series 6-Axis: C-/N-/VT-Series			
Vision integration	Vision Guide PV1 and CV2			
Software Features				
Max. # of feeders supported per robot controller (All-in-Ones)	2			
Max. # of feeders supported per robot controller (RC700A, RC700D & RC90B)	4			
Max. # of robots sharing the same feeder at the same time (RC700A with drive units only)	2			
Max. # of robots sharing the same feeder at the same time (RC90B & All-in-Ones)	1			
Max. # of unique parts per feeder running at the same time	4			
Max. # of parts per development environment project (Epson RC+)	32			
Purge software function (IntelliFlex 80 requires Purge Calibration)	Supported			
Options				
Purge hardware	Optional hardware required			
Integrated backlight options	White/Red/Infrared/Green/Blue			
Tray configuration options	ESD (Anti-static) Anti-stick Anti-rolling Medical Black			
Hopper sizes	0.16 L	2 L/3 L	10 L	15 L
What's in the box	Flexible Feeder, IntelliFlex Software, Power and Communication Cables			
Support	Customer Service (562) 290-5920 service@robots.epson.com Applications Support (562) 290-5930 applications@robots.epson.com Sales Inquiries (562) 290-5997 info@robots.epson.com			

FORCE GUIDE

Intuitive robot force guidance for high-precision performance

Powered by proprietary Epson Quartz Technology, Epson Force Guide enables Epson robots to detect six axes of force with precision down to 0.1 N. Driven by real-time servo system integration, Force Guide delivers fast, tactile feedback to guide robots for high-precision parts placement. Easy to set up, Force Guide features a point-and-click interface with pre-configured solutions and built-in objects, reducing the development time for precision applications.

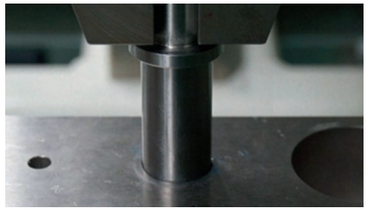
Advantage Epson

Drawing on our global expertise in robotic solutions, Epson created Force Guide as a tool to achieve higher productivity in automated manufacturing processes. Epson Force Guide features proprietary Quartz Technology, which provides remarkable rigidity and powerful performance, allowing customers to complete automation tasks that were previously not possible.

- **Epson Quartz Technology**
- **High rigidity**
- **Powerful performance**

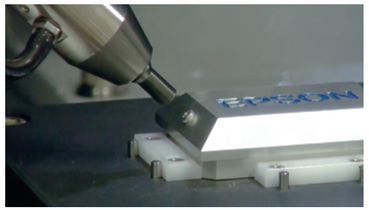
Force Guide applications

Force and torque sensors are an increasingly significant component for material testing, assembly, development and quality assurance. Because of their accuracy, versatility and reliability, they are being used by more and more companies around the world. Epson Force Guide provides a wide range of automation possibilities:



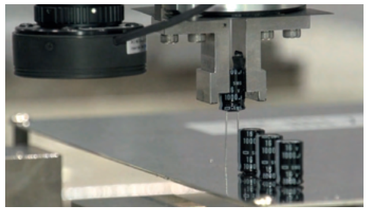
Parts and connector insertion

With Epson Force Guide, parts and connector insertion can be easily automated for everything from pin-in-socket insertion to high-precision valve assembly. Epson sensors detect misalignment. And, because of high sensitivity, the part or connector is easily inserted, damage-free.



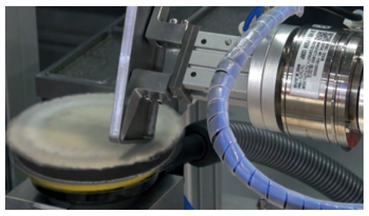
Screw driving

Thanks to real-time force/torque feedback, the smallest of screws can be easily tightened, even when there is deviation in angle or location. By detecting the force, the robot can successfully execute the task while preventing any stripping of the threads.



Delicate parts handling

Because of its tight integration with the servo system, Epson Force Guide makes it easy to handle glass and other delicate materials. Our quartz-based sensors allow for soft placement in applications that would otherwise result in breakage of glass or other fragile materials.



Grinding/polishing

Deburring and grinding of parts to accurately remove excess flash is possible with Epson Force Guide, despite deviations in casting or dimensions. The tool remains on its path, due to real-time force feedback. Similarly, polishing can be automated so as to keep the tool pressing with constant and precise force to the part.

Gear meshing

On assembly operations, Epson Force Guide provides the robot with the tools and data necessary to align and match the faces of various components, including multiple gears.

Force Guide tools

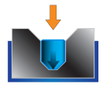
Pre-configured force guidance object tools provide a simple method for creating robot force-based motions and applications.

1 CONTACT
Find the object

2 ALIGN
Align the object, as needed

3 PROBE
Find the holes or steps needed

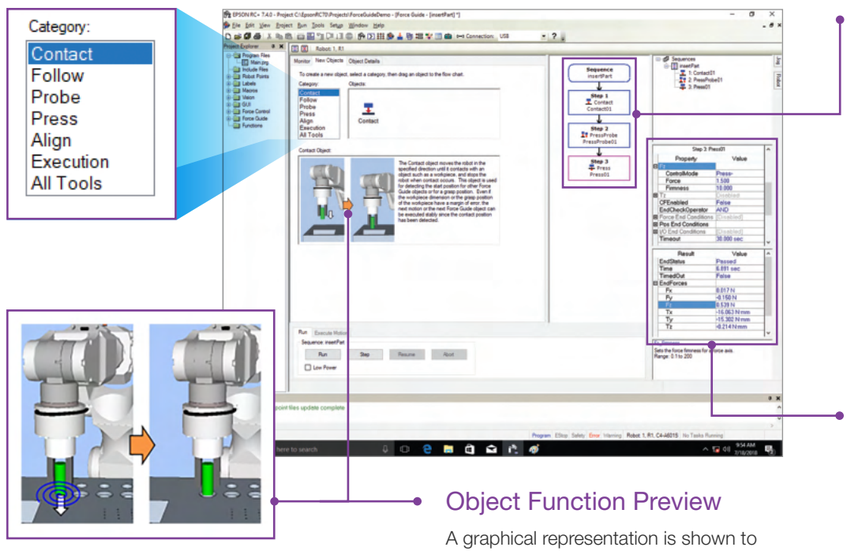
4 FOLLOW
Move the robot based on the force detected



5 PRESS
Continue to apply the necessary force to the object to complete placement of the part

Intuitive interface

Fully integrated in the Epson RC+ development environment, Epson Force Guide applications can be created and tested in an easy-to-use point-and-click fashion.



Force Guide Sequence

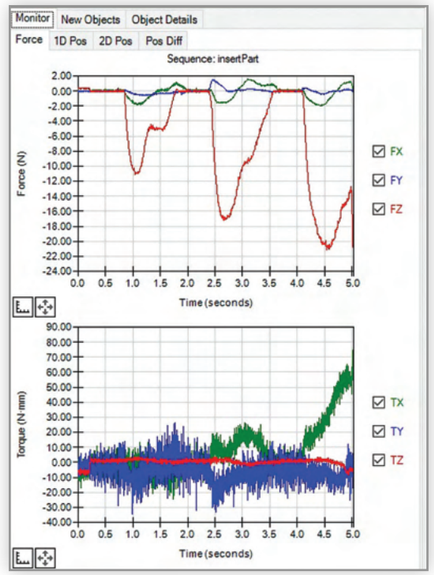
The Force Guide sequence flowchart provides a simple drag-and-drop mechanism for defining the force guidance operational flow (ordering of steps). This reduces the amount of programming required for Force Guide applications.

Object Properties and Results

Users can input and adjust force and torque data. The software automatically generates associated results based on input parameters.

Object Function Preview

A graphical representation is shown to illustrate the robot motions associated with specific Force Guide tools.



Real-time Force Guide monitoring

Epson Force Guide provides real-time graphical representations of both force and torque, allowing users to see and adjust force guidance based on object parameters. Epson Force Guide also provides visual feedback and records and displays data logs to ensure operational reliability.

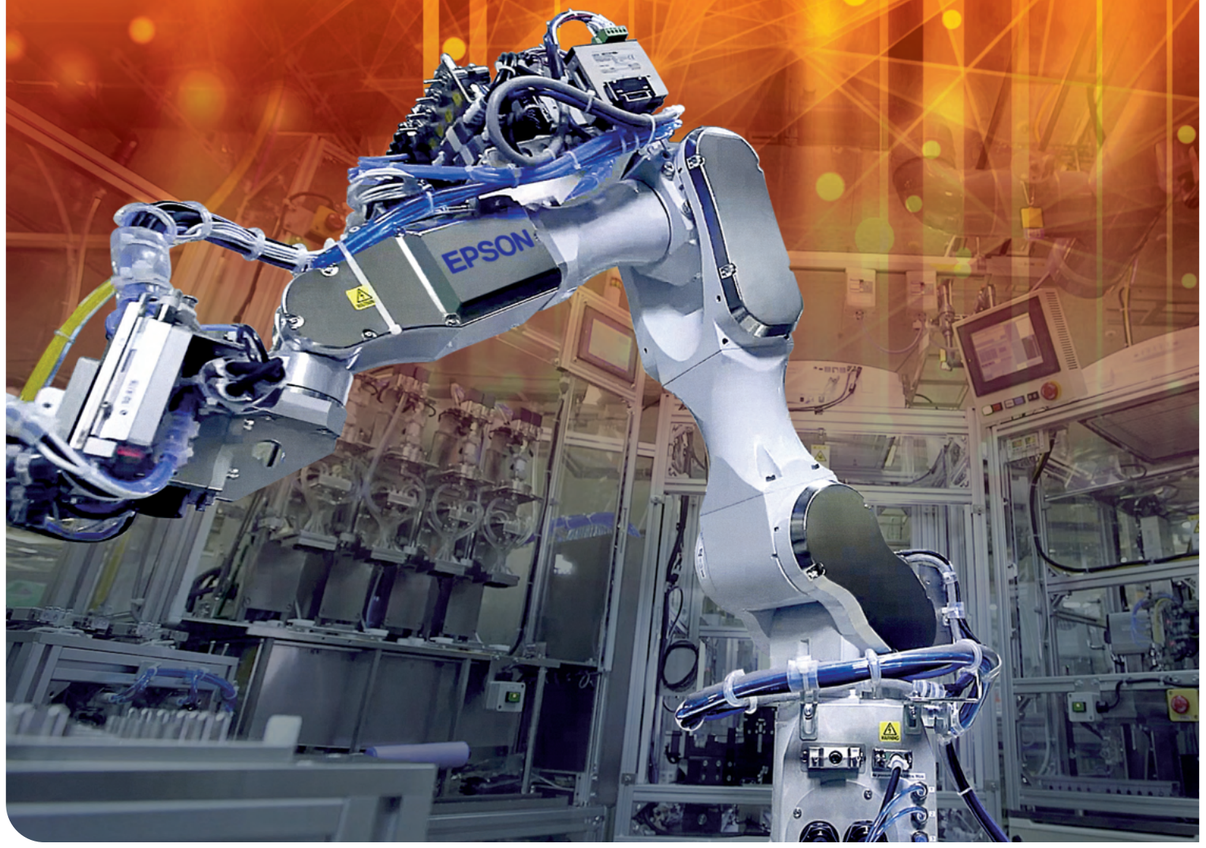
SPECIFICATIONS

Model No.		S250N	S250L	S250P	SH250LH	S250H	S2503		S2506	S25010
Compatible robots[1]		C4	C8 (Standard, Clean/ ESD) C12XL	C8 (Protected)	N6	N2	RS-Series	G3 GX4	G6 GX8	G10 G20
Cabling routing		External	Internal	Internal	Internal	Internal	Internal	External	Internal	Internal
Dimensions (diameter x height)		80 mm x 49 mm	88 mm x 49 mm	88 mm x 66 mm	85 mm x 48 mm	80 mm x 49 mm	80 mm x 52 mm		80 mm x 52 mm	80 mm x 52 mm
Weight[2]		460 g	520 g	680 g	460 g	460 g	620 g		620 g	640 g
Compatible robot controller[3]		RC700A, RC700D (GX4 and GX8)								
Measured degrees of freedom		6-Axis: 3 force components (Fx, Fy, Fz) and 3 torque components (Tx, Ty, Tz)								
Rated load	Force (Fx, Fy, Fz)	250 N								
	Torque (Tx, Ty, Tz)	18 Nm								
Maximum allowable static load	Force (Fx, Fy, Fz)	1,000 N								
	Torque (Tx, Ty, Tz)	36 Nm								
Measured resolution[4]	Force (Fx, Fy, Fz)	± 0.1 N or less (5 sec, 25 °C)								
	Torque (Tx, Ty, Tz)	± 0.003 Nm or less (5 sec, 25 °C)								
Measurement accuracy[5]		± 5% RO or less								
Operating environment	Temperature	-10 °C ~ 40 °C								
	Humidity	10% – 80% relative humidity, no condensation								
Protection class		IP20	IP20	IP67	IP20	IP20	IP20	IP20	IP20	IP20
What's in the box		Force Sensor, Force Control Board, Cables								
Safety standards		CE Mark: EMC Directive, KC Mark								
Support		Customer Service (562) 290-5920 service@robots.epson.com Applications Support (562) 290-5930 applications@robots.epson.com Sales Inquiries (562) 290-5997 info@robots.epson.com								

1 Robots not supported: G1, LS-Series, TB-Series, EZ Modules.
2 Weight includes force sensor and mounting flange; does not include control board and cables.
3 Controllers not supported: RC90B and All-in-One.
4 The measurement resolution including the noise level and time drift (25 °C), when the measurement time is 5 seconds.
5 The measurement accuracy when the measurement time is 6 minutes.

Options

From Vision Guide and Force Guide to GUI Builders, teach pendants, conveyor tracking and fieldbus I/O, Epson offers the options you need to enhance your robot system.



SPECIFICATIONS

Controller Options

	All-in-One (TB- and VT-Series)	RC90B (LSB-Series)	RC700A (G-, RS-, C-, N-Series)	RC700D (GX-Series)
Teach pendant (TP2)	●	●	●	—
Teach pendant (TP3)	●	—	●	●
Conveyor tracking	—	●	●	●
PG cards (external axis control)	—	●	●	●
Emergency stop switch	●	●	●	●
RS-232C cards	—	●	●	●
I/O expansion cards	—	●	●	●
Fieldbus I/O (slave)	●	●	●	●
Fieldbus I/O (master)	●	●	●	●
I/O cable kit	—	●	●	●
Analog 1/0	—	●	●	●
Euromap 67	—	●	●	●
Force Guide	—	—	●	●
Parts Feeding	●	●	●	●

Software Options

	All-in-One	RC90B	RC700A	RC700D
Vision Guide (7.0)	●	●	●	●
RC+ 7.0 API	●	●	●	●
ECP	●	●	●	●
GUI Builder 7.0	●	●	●	●
OCR	●	●	●	●
Add-On Instructions	●	●	●	●

Robot Manipulator Options

	T3-B/ T6-B	LS3-B/ LS6-B/ LS10-B/ LS20-B	RS3/ RS4	G1	GX4/ GX8	G6/ G10/ G20	N2/N6	C4	C8/ C12XL	VT6L
External wiring units	—	—	—	—	●	●	—	—	—	●
Tool adapters/ISO flange	●	●	●	●	●	●	●	—	●	●
Brake release units	—	—	—	—	—	—	●	●	●	—
Power and signal cables	—	●	●	●	●	●	●	●	●	●
Camera mounting bracket	●	●	●	—	●	●	●	●	●	●
External drive units	—	—	●	●	—	●	—/●	●	●/—	—
UL 1740	—	—	●	●	●	●	—	●	●	—

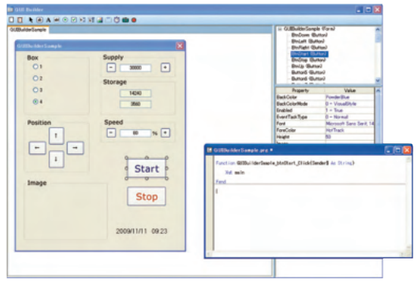
GUI Builder

COMPATIBLE CONTROLLERS

All-in-One | RC90B | RC700A | RC700D

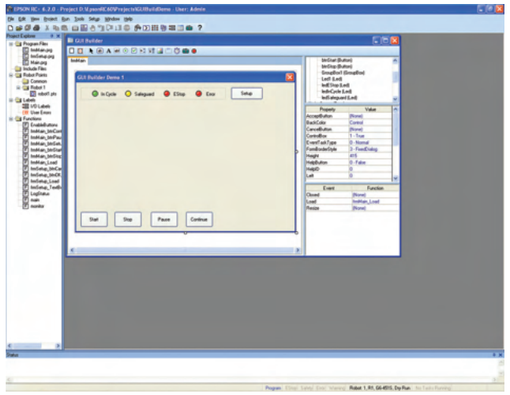
Easily create a Graphical User Interface (GUI) for operators

- Fully integrated within Epson RC+ to reduce overall development time
- Create GUIs without Visual Studio or other third-party software tools
- Create and debug GUI forms from your Epson RC+ Project
- Form and Control Events are executed as SPEL+ tasks
- Perfect for novices and experts alike
- Works with RC700A, RC700D, RC90B and All-in-One controllers



The GUI Builder Window

GUI Builder has five main areas of use for creating and modifying user GUIs. These include: Toolbar Buttons, Design Area, Forms Explorer, Property Grid and Events Grid.



GUI Builder area definitions

DESIGN AREA

Where forms are displayed at design time.
Each opened form is displayed on its own tab. You can easily switch between forms by clicking on the tab or double-clicking the form in the Forms Explorer.

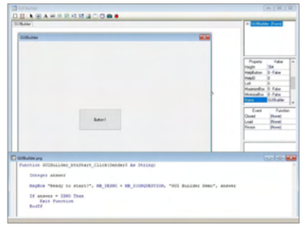
Steps to Use GUI Builder

STEP 1

Create a new form, click the Button control from the GUI Builder toolbar and drag it to the form.

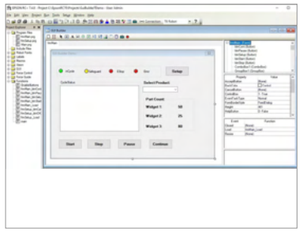
STEP 2

Double-click the button and the Code Editor will appear. Add the SPEL+ code you want to execute when the button is clicked from your application.



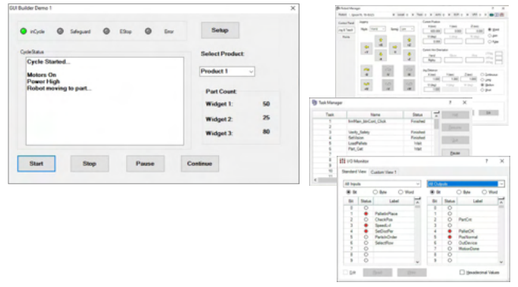
STEP 3

Add more graphic components on your form and associated SPEL+ codes as required for your application.



STEP 4

Run the application from the Epson RC+ Run window or set it up to have the GUI come up automatically. You can also bring up Epson RC+ dialogs like the I/O monitor shown here.



TOOLBAR BUTTONS

Contains the various controls to be put on a GUI Builder form. Many of the common controls are supported, such as Button, Label, Textbox, Radio Button and Checkbox. However, there are also some controls unique to Epson that help reduce development time for items routinely needed for robot systems. Some of these unique controls include the Video Box control (to display the Vision Guide image) and the LED control (to interface with the Epson robot I/O).

FORMS EXPLORER

A tree that contains each form for the current project and its associated controls. When a new form or control is created, it is added to the tree. Double-clicking on a form opens the form in its own tab in the design area.

PROPERTY GRID

Used to display and edit forms and control properties. When you select a form or control, the associated properties are displayed in the grid. You can edit the values for properties, thus changing the characteristics of the specific control.

EVENTS GRID

Used to display and change events for the associated form or control. Each event has a user function (written in SPEL+ code) that is called when the event occurs. This gives the user complete flexibility to program what happens when specific events occur.

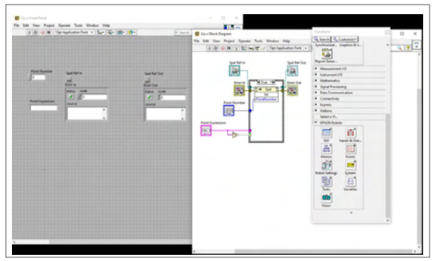
RC+ 7.0 API

COMPATIBLE CONTROLLERS

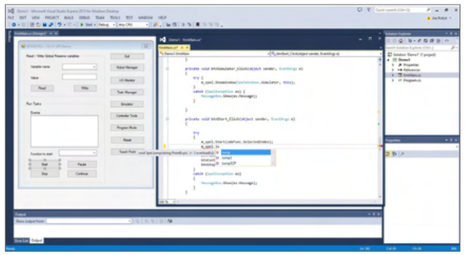
All-in-One | RC90B | RC700A | RC700D

Program and execute robot applications in a familiar MS Windows OS environment

- Robots can be controlled using Visual Basic®, Visual C++®, Visual C#®, LabVIEW™ and other third-party programming languages
- Robot status and variable values can be captured
- Vision Guide integration for easy image display on user GUIs
- Third-party .Net interface and database design tools can also be used for program development
- The following Epson RC+ windows and dialogs can be called from within a .Net application:
  - Robot Manager
  - I/O Monitor
  - Task Manager
  - Maintenance Dialog
  - Simulator
  - Force Monitor



LabVIEW



Visual C®

Add-On Instructions (AOI) for Allen Bradley®

COMPATIBLE CONTROLLERS

RC90B | RC700A | RC700D

For integration with systems using Allen Bradley PLC-based programming[1]

- Ideal for both basic and complex programming tasks—initiates simple solutions or highly structured programs, all with ladder-logic programming
- Single point of control—machine control via a PLC

1 An EtherNet/IP board is required to enable communication between the robot controller and the programmable logic controller.

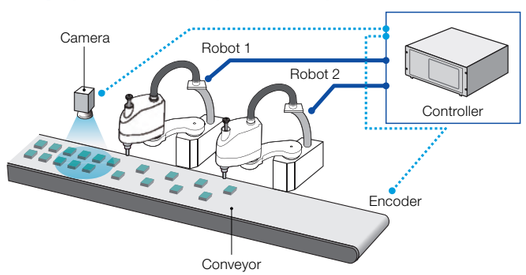
Conveyor Tracking

COMPATIBLE CONTROLLERS

RC90B | RC700A | RC700D

Precision tracking for high-productivity pick-and-place operation

- Supports vision- or sensor-based conveyor tracking
- Vision Guide software detects moving parts for pick-and-place handling
- Multi-conveyor, multi-tool setups are supported
- Automate manual kitting/packaging tasks and help maintain productivity with continuous conveyor operation; ideal for product assembly



Fieldbus I/O (Master)

COMPATIBLE CONTROLLERS

All-in-One | RC90B | RC700A | RC700D

Bidirectional high-speed peripheral connectivity

- Support for DeviceNet, PROFIBUS and EtherNet/IP networked peripherals (1,024-point I/O)
- Requires user PC for master board
- Must be connected to robot controller during operation

Fieldbus I/O (Slave)

COMPATIBLE CONTROLLERS

All-in-One | RC90B | RC700A | RC700D

High-speed peripheral connectivity

- Support for DeviceNet, PROFIBUS, CC-Link®, EtherNet/IP, EtherCAT and PROFINET® networked peripherals (256-point I/O)

Teach Pendant TP2

COMPATIBLE CONTROLLERS

All-in-One | RC90B | RC700A

Easy-to-use pendant

- Universal design ensures ease of use for both right-handed and left-handed operators

Teach Pendant TP3

COMPATIBLE CONTROLLERS

All-in-One | RC700A | RC700D

Powerful pendant for both teaching and robot operation

- 10" color touchscreen panel
- 1280 x 800 high-definition screen resolution
- User-friendly GUI
- Ability to make robot parameter changes
- High-speed test mode
- IP65-rated enclosure is sealed against oil and dust for reliable operation in adverse conditions
- Shock-resistant construction helps protect unit from impact damage
- Universal design ensures ease of use for both right-handed and left-handed operators

Camera Mounting Bracket

COMPATIBLE ROBOT MANIPULATORS

G3 | GX4 | G6 | GX8 | G10 | G20 | LS3-B | LS6-B | LS10-B | LS20-B | RS3 | RS4 | T3-B | T6-B | N2 | N6 | C4 | C8 | C12 | VT6L

Easily mount cameras to robot arm

Bracket design varies according to robot; please specify model when ordering.

OCR

COMPATIBLE CONTROLLERS

All-in-One | RC90B | RC700A | RC700D

Optical Character Recognition (OCR) of text on parts and labels

- For use with optional Vision Guide system
- Enables you to specify the font, font size and number of characters of text that you want to read from an image
- A font creation function lets you create SEMI fonts and user-defined fonts from imaged characters or ASCII conversion files

PG Motion System

COMPATIBLE CONTROLLERS

RC90B | RC700A | RC700D

Control peripheral devices for fully integrated process automation*

- Epson RC+ Software and pulse generator (PG) cards enable control of multiple third-party drives and motors
- PG robots and standard Epson RC+ system robots can be operated simultaneously and controlled using the same commands
- PG cards can be used to control X/Y tables, slides, rotary tables and a wide range of other production/inspection line peripherals
- Each PG card has 4 channels and can support from 1 to 4 robots; up to 4 cards can be installed on the RC700A

*Drivers and motors for third-party devices not included.

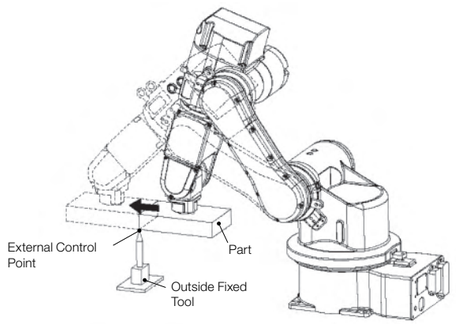
ECP

COMPATIBLE CONTROLLERS

All-in-One | RC90B | RC700A | RC700D

External Control Point (ECP) operation for precise positioning

- For processes requiring the workpiece to be moved against a fixed tool, external control points can be used to ensure precise positioning
- Up to 16 external control points can be set



RC700A DU Drive Unit

COMPATIBLE ROBOT MANIPULATORS

G1 | G3 | G6 | G10 | G20 | RS3 | RS4 | N6 | C4 | C8

Control multiple robots with a single RC700A controller

Emergency Cable Kit

COMPATIBLE CONTROLLERS

All-in-One | RC90B | RC700A | RC700D

Convenient wiring of the safety circuit

- Cable and connectors for easy connection of the emergency stop switch

I/O Cable Kit

COMPATIBLE CONTROLLERS

RC90B | RC700A | RC700D

Cables and connectors for easy connectivity with no soldering required

- A wide range of I/O cables and connectors are available

RS-232C Cards

COMPATIBLE CONTROLLERS

RC90B | RC700A | RC700D

Expanded Serial port connectivity

- 2-port RS-232C cards to connect to Serial interface devices

I/O Expansion Cards

COMPATIBLE CONTROLLERS

RC90B | RC700A | RC700D

Expanded input/output flexibility

- 24 inputs/16 outputs per board

External Wiring Units

COMPATIBLE ROBOT MANIPULATORS

G6 | GX8 | G10 | G20 | VT6L

Simplifies wiring when mounting end-effector options

- Enables easy, on-site connection of external wiring by users
- Ideal for connecting Vision Guide system camera cables or other wiring

Tool Adapters/ ISO Flanges

COMPATIBLE ROBOT MANIPULATORS

G1 | G3 | GX4 | G6 | GX8 | G10
G20 | LS3-B | LS6-B | LS10-B | LS20-B | RS3
RS4 | T3-B | T6-B | N2 | N6 | C4L
C8 | C8L | C8XL
C12XL | VT6L

Enhances handling/processing versatility and simplifies end-effector changes

Brake Release Units

COMPATIBLE ROBOT MANIPULATORS

N2 | N6 | C4 | C8 | C12

Releases brakes so robot arm can be moved by hand when power is off

Euromap 67 Interface

COMPATIBLE ROBOT MANIPULATORS

G1 | G3 | GX4 | G6 | GX8 | G10
G20 | LS3-B | LS6-B | LS10-B | LS20-B | RS3
RS4 | N2 | N6 | C4 | C4L | C8
C8L | C8XL | C12XL

Epson solution complies with Euromap 67, the standard for connection between injection molding and robots

Certified Epson Robots Training Courses

Epson offers a wide variety of high-quality, certified courses designed to help you learn how to quickly and effectively program and operate our robot and vision products. Students can attend courses online or in-person at our Epson Training Center in California or at any of our regional Certified Training Centers. All courses are taught by Epson-certified instructors in a structured environment designed for hands-on learning.

Available Courses

Epson RC+ Core 1 Robot Training

Core 1 provides in-person instruction and hands-on labs to get students quickly comfortable using the Epson RC+ environment and Epson SPEL+ programming language, which is used on all Epson SCARA and 6-Axis robots.

Epson RC+ Core 2 Advanced Robot Training

Core 2 focuses on integration of Epson robots into today's complex automation systems. Advanced use of motion control, logic and integration are emphasized in this two-day course.

Epson Vision Guide Training

Designed to get users up and running with the Epson Vision Guide system to create vision sequences for robot motion guidance, inspection and gauging. In this two-day course, students will learn how to configure vision tools and objects and perform calibrations.

Epson RC+ Express No-Code Robot Training

Epson RC+ Express training provides students with hands-on experience creating robotic applications using the latest no-code teaching environment from Epson. This one-day course is ideal for users who are new to automation.

Contact Information

U.S. and Canada

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Los Alamitos, CA 90720

epson.com/robottraining